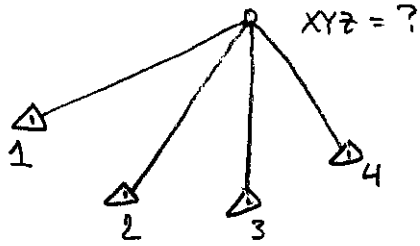


1. 3D trilateration problem:



$$\begin{aligned} n &= 4 \\ n_0 &= 3 \\ r &= 1 \end{aligned}$$

use method of indirect observations
 $\Rightarrow \mu = n_0 = 3$  :  $x, y, z$  of the unknown point

 $C = n$ , one equation per obs.

initial approximations are not easy here, although it converges over a wide range - suggest 3D CAD display with spheres

$$d_i = [(x_i - x)^2 + (y_i - y)^2 + (z_i - z)^2]^{1/2}$$

$$F_i = d_i - [(x_i - x)^2 + (y_i - y)^2 + (z_i - z)^2]^{1/2} = 0$$

$$\frac{\partial F_i}{\partial x} = \frac{x_i - x}{[ \cdot ]^{1/2}}, \quad \frac{\partial F_i}{\partial y} = \frac{y_i - y}{[ \cdot ]^{1/2}}, \quad \frac{\partial F_i}{\partial z} = \frac{z_i - z}{[ \cdot ]^{1/2}}$$

$$f_i = -F_i(l, x^0), \quad \sigma_0^2 = (0.4)^2, \quad w_{ii} = \sigma_0^2 / \sigma_i^2$$

chose  $x^0 = 5560$ ,  $y^0 = 10500$ ,  $z^0 = 400$

after 5 iterations,

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5654.751 \\ 10510.180 \\ 483.976 \end{bmatrix}$$

$$V = \begin{bmatrix} -1.48 \\ 4.61 \\ -0.06 \\ 1.15 \end{bmatrix}$$

(1)  $v_1$  large compared to a priori  $\sigma$ 's. That should worry you.

(2)  $v_3$  much smaller than others consistent with smaller a priori  $\sigma$

see listing for implementation in MATLAB.

```

trilat3d.m
% trilat3d.m 10-oct-07
% do ce506 homework problem, indirect obs.
%
% di = sqrt ( (xi - x)^2 + (yi - y)^2 + (zi - z)^2 )
%
% Fi = di - ( (xi - x)^2 + (yi - y)^2 + (zi - z)^2 )^(1/2) = 0
%
% dF/dx = - 0.5*(...)^(-1/2) * 2*(xi-x)*(-1) = (xi-x) / (...)^1/2
% dF/dx = (xi-x) / (...)^1/2
% dF/dy = (yi-y) / (...)^1/2
% dF/dz = (zi-z) / (...)^1/2
%
% f = -F
%
% n=4
% no=3;
% r=1
% u=3
% c=r+u  chk

n=4;
no=3;
r=1;
u=3;
c=r+u;

% define observations

d1=698.00;
d2=628.40;
d3=483.05;
d4=430.30;
l=[d1;d2;d3;d4];

% define the sigmas and weights

sigd1=0.40;
sigd2=0.40;
sigd3=0.05;
sigd4=0.40;
% define a priori sigma-naught squared
sig0=0.40;
W=eye(4);
W(1,1)=sig0^2/sigd1^2;
W(2,2)=sig0^2/sigd2^2;
W(3,3)=sig0^2/sigd3^2;
W(4,4)=sig0^2/sigd4^2;

% the points

x1= 5075.00;
y1=10550.00;
z1= 100.00;
x2= 5320.00;
y2=10115.00;
z2= 120.00;
x3= 5560.00;
y3=10190.00;
z3= 135.00;
x4= 5815.00;
y4=10640.00;
z4= 105.00;

x= 5560.0;
y=10500.0;
z= 400.0;

B=zeros(c,u);
f=zeros(c,1);
max_iter=10;
iter=1;
keep_going=1;
% convergence variables
phi=10;
last_phi=20;
threshold=1.0e-06;

while keep_going == 1
% dF/dx = (xi-x) / (...)^1/2
% dF/dy = (yi-y) / (...)^1/2
% dF/dz = (zi-z) / (...)^1/2
d10=sqrt((x1-x)^2 + (y1-y)^2 + (z1-z)^2);
d20=sqrt((x2-x)^2 + (y2-y)^2 + (z2-z)^2);

```

```

trilat3d.m
d30=sqrt((x3-x)^2 + (y3-y)^2 + (z3-z)^2);
d40=sqrt((x4-x)^2 + (y4-y)^2 + (z4-z)^2);

% make coefficients of the condition equations

B(1,:)=[(x1-x)/d10 (y1-y)/d10 (z1-z)/d10];
B(2,:)=[(x2-x)/d20 (y2-y)/d20 (z2-z)/d20];
B(3,:)=[(x3-x)/d30 (y3-y)/d30 (z3-z)/d30];
B(4,:)=[(x4-x)/d40 (y4-y)/d40 (z4-z)/d40];

f(1)=- (d1 - sqrt((x1-x)^2 + (y1-y)^2 + (z1-z)^2));
f(2)=- (d2 - sqrt((x2-x)^2 + (y2-y)^2 + (z2-z)^2));
f(3)=- (d3 - sqrt((x3-x)^2 + (y3-y)^2 + (z3-z)^2));
f(4)=- (d4 - sqrt((x4-x)^2 + (y4-y)^2 + (z4-z)^2));

if iter == 1
    disp('iteration 1 B,f,W');
    B
    f
    W
end

% now solve and update and check convergence

N=B'*W*B;
t=B'*W*f;
iter
del=inv(N)*t
x=x + del(1);
y=y + del(2);
z=z + del(3);
v=f-B*del;
phi=v'*W*v;

if( abs(phi-last_phi)/last_phi < threshold )
    keep_going=0;
    disp('we have converged');
end
last_phi=phi;
if iter > 10
    keep_going=0;
    disp('too many iterations');
end
iter=iter+1;
end;

disp('final coordinates');
[x y z]
disp('residuals');
v=f - B*del
lhat=l + v

```

```

trilat3d
iteration 1 B,f,W
B =
    -0.847201961354498    0.0873404083870616    -0.52404245032237
    -0.450173684486989    -0.722153618864545    -0.525202631901488
                                0    -0.760121344351798    -0.649781149203957
    0.615486138525602    0.337913958406213    -0.71203298378452

f =
    -125.527293227005
    -95.272435527856
    -75.2203787118939
    -15.9933502826681

W =
    1    0    0    0
    0    1    0    0
    0    0    64    0
    0    0    0    1

iter =
1
del =
    84.2012454507889
    11.2968278498699
    102.452344553807

iter =
2
del =
    10.7735478429505
    -1.00763919322787
    -18.2131730293733

iter =
3
del =
    -0.223312424702833
    -0.108807783498614
    -0.262881421569946

iter =
4
del =
    -0.000229557855063712
    -3.86830203854812e-005
    5.36510426031894e-005

iter =
5
del =
    -2.64788004749516e-007
    -4.19623422490706e-007
    4.49683936952399e-007

we have converged
final coordinates
ans =
    5654.75125104639    10510.1803417705    483.97634420359

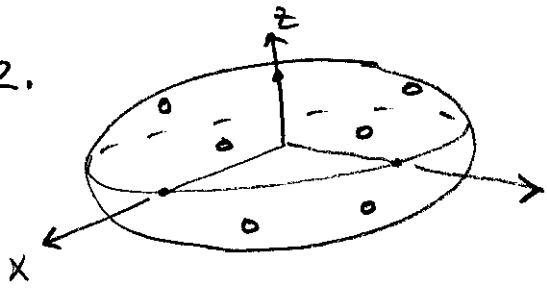
residuals
v =
    -1.48370357950332
    4.61238671828909
    -0.0616568230310241
    1.15784808013185

lhat =
    696.516296420497
    633.012386718289
    482.988343176969
    431.457848080132

diary off

```

2.



$$N = 6 \times 3 = 18$$

$$N_0 = 2 + 6 \times 2 = 14$$

$$r = 4$$

$$m = 2 \quad a, b$$

$$c = r + m = 6, \text{ one equation per point}$$

use general least squares = mixed model

$$\frac{x_i^2 + y_i^2}{a^2} + \frac{z_i^2}{b^2} = 1 \quad , \quad F_i = 1 - \frac{x_i^2 + y_i^2}{a^2} - \frac{z_i^2}{b^2} = 0$$

$$\left. \begin{aligned} \frac{\partial F_i}{\partial x_i} &= -\frac{2x_i}{a^2} \quad , \quad \frac{\partial F_i}{\partial y_i} = -\frac{2y_i}{a^2} \quad , \quad \frac{\partial F_i}{\partial z_i} = -\frac{2z_i}{b^2} \end{aligned} \right\} \text{for } A \text{ matrix}$$

$$\frac{\partial F_i}{\partial a} = \frac{2(x_i^2 + y_i^2)}{a^3} \quad , \quad \frac{\partial F_i}{\partial b} = \frac{2z_i^2}{b^3}$$

$$f_i = -F - A(l - l^0)^2$$

use ~WG8-84 parameters as initial approximations:

$$a \approx 6378.0 \text{ km} \quad , \quad b \approx 6378.0 \text{ km}$$

converged in 2-3 iterations, with

$$\begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 6378.141 \\ 6356.744 \end{pmatrix} \quad , \quad V^T = \begin{bmatrix} -0.007 & -0.003 & -0.006 & 0.002 & 0.002 & -0.014 \\ -0.004 & 0.004 & 0.006 & 0.005 & 0.006 & -0.013 \\ 0.000 & 0.000 & 0.000 & -0.000 & 0.000 & 0.004 \end{bmatrix}$$

Notes: as expected, small  $\sigma$  for  $x$ 's  $y$ 's  $z$ 's yields small residuals, my solution code did not terminate after convergence.

```

% ellfit.m 2-oct-07
% solve homework 2 problem 2

n=6*3;
n0=2+6*2;
r=n-n0;
u=2;
c=r+u;

sig=0.02;
sig5=0.002;
sig0=0.02;
W=eye(n);
for i=1:n
    W(i,i)=sig0^2 / sig^2;
end
idx=(5-1)*3 + 1;
W(idx,idx)= sig0^2 / sig5^2;
W(idx+1,idx+1)=sig0^2 / sig5^2;
W(idx+2,idx+2)=sig0^2 / sig5^2;

x=[4600;1000;-3200;-2100;-2700;200];
y=[2200;1000;3400;-2500;-5000;-500];
z=[3818.7;-6198.5;4330.6;5460.75;-2886.95;-6334.05];
a=6378;
b=6378;
l=[x(1);y(1);z(1);x(2);y(2);z(2);x(3);y(3);z(3);x(4);y(4);z(4);x(5);y(5);z(5);x(6);y(6);z(6)];
l0=l;
for iter=1:10
    A=zeros(c,n);
    B=zeros(c,u);
    f=zeros(c,1);
    F=zeros(c,1);
    X=[l0(1);l0(4);l0(7);l0(10);l0(13);l0(16)];
    Y=[l0(2);l0(5);l0(8);l0(11);l0(14);l0(17)];
    Z=[l0(3);l0(6);l0(9);l0(12);l0(15);l0(18)];
    for i=1:6
        col=(i-1)*3+1;
        A(i,col)=-2*X(i)/(a^2);
        A(i,col+1)=-2*Y(i)/(a^2);
        A(i,col+2)=-2*Z(i)/(b^2);
        B(i,1)=2*(X(i)^2 + Y(i)^2)/(a^3);
        B(i,2)=2*(Z(i)^2)/(b^3);
        F(i)=1-(X(i)^2 + Y(i)^2)/(a^2) - (Z(i)^2)/(b^2);
    end
    f=-F - A*(l-l0);
    Q=inv(W);
    Qe=A*Q*A';
    We=inv(Qe);
    del=inv(B'*We*B)*B'*We*f;
    del
    a=a+del(1);
    b=b+del(2);
    k=We*(f-B*del);
    v=Q*A'*k;
    l0=l+v;
    if(iter == 1)
        A
        B
        f
    end
end
end
a
b
v

```

```

ellfit
del =      0.141195453773856
          -21.3630940379217
A =
Columns 1 through 4
-0.00022616156333099      -0.000108164225940908      -0.000187748513454794
0
-4.91655572458674e-005      0      0
0      0      0
0      0      0
0      0      0
0      0      0
Columns 5 through 8
0      0      0
-4.91655572458674e-005      0.000304752706588509      0
0
-0.000167162894635949      0      0.000157329783186776
0      0      0
0      0      0
0      0      0
Columns 9 through 12
0      0      0
0      0      0
-0.000212916362208953      0      0
0
-0.00026848081673037      0.000103247670216322      0.000122913893114669
0      0      0
0      0      0
Columns 13 through 16
0      0      0
0      0      0
0      0      0
0      0      0
0.000132747004563842      0.000245827786229337      0.000141938505490957
0
-9.83311144917348e-006      0      0
Columns 17 through 18
0
0
0
0
0
0
2.45827786229337e-005      0.000311417097873186
B =
0.000200424033927964      0.000112410669227002
1.54172333790741e-005      0.000296175862619767
0.000168047843831908      0.000144568140197882
8.21738539104651e-005      0.000229869335208587
0.000248911232905152      6.42473139584694e-005
2.23549883996575e-006      0.0003092711616155
f =
-0.00237013163881294
-0.00632961685969546
-0.00306762692899826
-0.0048942698993415
-0.00133739405191152
-0.00660525980752069
del =
1.98155609665469e-006
0.106744093385646
del =
6.70410926604951e-009

```

```
2.66645939635962e-006
del =
  2.16864070104461e-013
-1.22098511856628e-013
del =
  2.29728833612414e-013
-2.00928249732835e-013
del =
  2.32591127347775e-013
-2.19027487119439e-013
del =
  2.35017788650232e-013
-2.30873913736884e-013
del =
  2.35017788650232e-013
-2.30873913736884e-013
del =
  2.35017788650232e-013
-2.30873913736884e-013
del =
  2.35017788650232e-013
-2.30873913736884e-013
a =
  6378.14119744203
b =
  6356.74365272192
v =
-0.00690299682795318
-0.00330143326554282
-0.00576918202102412
  0.00226724710356425
  0.00226724710356425
-0.0141483022932827
-0.00467754575515591
  0.00496989236485316
  0.00637286919263785
  0.00506295861504281
  0.00602733168457478
-0.0132542827964667
-2.38478079730187e-005
-4.41626073574421e-005
-2.56710023586623e-005
-0.000140126460143534
  0.000350316150358834
  0.00446776686736413
diary off
```