

$w_i \sim \frac{1}{\sigma_i^2}, w_i = \frac{\sigma_0^2}{\sigma_i^2}$

σ_0^2 : prop. constant value arbitrary

(1) σ^2 of commonly occurring obs
 (2) 1.0

$$W = \begin{bmatrix} \frac{\sigma_0^2}{\sigma_1^2} & & & 0 \\ & \frac{\sigma_0^2}{\sigma_2^2} & & \\ & & \dots & \\ 0 & & & \frac{\sigma_0^2}{\sigma_n^2} \end{bmatrix}$$

$$W = \sigma_0^2 \begin{bmatrix} \frac{1}{\sigma_1^2} & & & \\ & \frac{1}{\sigma_2^2} & & \\ & & \dots & \\ & & & \frac{1}{\sigma_n^2} \end{bmatrix}, W = \sigma_0^2 \Sigma^{-1}$$

$Q = \frac{1}{\sigma_0^2} \Sigma, \Sigma = \sigma_0^2 Q$

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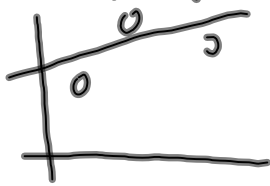
W : original observations: diagonal
 derived observation: usually not diagonal

How to get cond. eqns O/O from cond eqns I/O, if not obvious

| | | | | |
|------------------|------------|-----|-----------------|-----------------|
| $\frac{n}{-n_0}$ | I/O | r | $+ n_0$ | $= n$ |
| r | | | | |
| | base # eqn | | 1 per parameter | total cond. eqn |

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Example of : parameter eqns \rightarrow no parameters 9-3



$$y = mx + b$$

$$n=3$$

$$n_0=2$$

$$\underline{r=1}$$

$$y_1 = mx_1 + b$$

$$y_2 = mx_2 + b$$

$$b = y_1 - mx_1$$

$$y_3 = mx_3 + b$$

$$y_2 = mx_2 + y_1 - mx_1 = m(x_2 - x_1) + y_1$$

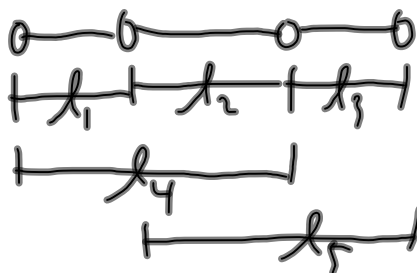
$$y_3 = mx_3 + y_1 - mx_1 = m(x_3 - x_1) + y_1$$

$$m = \frac{y_2 - y_1}{x_2 - x_1}, \quad y_3 = \frac{y_2 - y_1}{x_2 - x_1} \cdot x_3 - x_1 + y_1$$

$$\frac{y_2 - y_1}{x_2 - x_1} = \frac{x_2 - x_1}{x_2 - x_1}$$

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Derive matrix approach to LS using O/O method 9-4



$$n=5$$

$$n_0=3$$

$$\underline{r=2}$$

$$\hat{l}_4 = \hat{l}_1 + \hat{l}_2$$

$$\hat{l}_5 = \hat{l}_2 + \hat{l}_3$$

$$\hat{l}_4 - \hat{l}_1 - \hat{l}_2 = 0$$

$$\hat{l}_5 - \hat{l}_2 - \hat{l}_3 = 0$$

$$\begin{bmatrix} -1 & -1 & 0 & 1 & 0 \\ 0 & -1 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} l_1 + v_1 \\ l_2 + v_2 \\ \vdots \\ l_5 + v_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$Av = \underbrace{d - Al}_f$$

$$Av = f$$

$n \quad n_1 \quad r_1$

$$\hat{e} = d$$

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$$\Phi = v^T W v, \text{ use LM} \quad 9-5$$

$$\Phi' = v^T W v - 2k_1(\dots) - 2k_2(\dots) \dots$$

$$\Phi' = v^T W v - \frac{2k^T (Av - f)}{2(Av - f)^T k} \quad \min_{v, k}$$

$$\frac{\partial \Phi'}{\partial v} = \cancel{2} v^T W - \cancel{2} k^T A = 0 \quad (\text{row vector})$$

$$\frac{\partial \Phi'}{\partial k} = -\cancel{2} (Av - f)^T = 0 \quad \text{" "}$$

$$Wv - A^T k = 0 \quad \text{col. vector}$$

$$\text{transpose:} \quad -Av = -f$$

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$$\begin{bmatrix} W & -A^T \\ -A & 0 \end{bmatrix} \begin{bmatrix} v \\ k \end{bmatrix} = \begin{bmatrix} 0 \\ -f \end{bmatrix} \quad \text{full normal eqns 9-6} \\ \text{L.M.}$$

 $n+r \times n+r$

$$Wv - A^T k = 0 \quad (W^{-1} = Q)$$

$$v - QA^T k = 0, \quad \boxed{v = QA^T k} \quad W_e = Q_e^{-1}$$

$$-Av = -f$$

$$Av = f \leftarrow$$

$$\underbrace{AQA^T}_{Q_e} k = f$$

 Q_e

$$\boxed{k = W_e f} \leftarrow$$

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level network

$l = \begin{pmatrix} 10 \\ 8 \\ 3 \\ 4 \\ 1 \end{pmatrix}$

$n=5$ $q=0$ $g=7$
 $n_0=3$
 $r=2$

$\hat{l}_3 - \hat{l}_1 + \hat{l}_2 = 0$
 $\hat{l}_4 - \hat{l}_5 - \hat{l}_3 = 0$

$$\begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ -1 & 1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \cdot l$$

A

v

f

$W = \underline{I}$

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$k = W e f$

$k = (A Q A^T)^{-1} f$

$v = Q A^T k$

$k = \begin{pmatrix} -0.375 \\ -0.125 \end{pmatrix}$

g-8

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