

$$F_1 = \hat{l}_1^2 + \hat{l}_2^2 - \hat{l}_3^2 = 0$$

$$F_2 = \hat{l}_4 + \hat{l}_r - \pi/2 = 0$$

$$F_3 = \hat{l}_4 - \tan^{-1}(\hat{l}_2/\hat{l}_1)$$

$$\frac{d}{dx} \tan^{-1} u = \frac{1}{1+u^2} \cdot \frac{du}{dx}$$

$$\frac{\partial F_1}{\partial l_1} = 2l_1 | l^0, \quad \frac{\partial F_1}{\partial l_2} = 2l_2 | l^0, \quad \frac{\partial F_1}{\partial l_3} = -2l_3$$

$$\frac{\partial F_2}{\partial l_4} = 1, \quad \frac{\partial F_2}{\partial l_r} = 1,$$

$$\frac{\partial F_3}{\partial l_1} = -\frac{1}{1 + \left(\frac{l_2}{l_1}\right)^2} \cdot (-1) \frac{l_2}{l_1^2} = \frac{l_2}{l_1^2 + l_2^2} | l^0$$

$$\frac{\partial F_3}{\partial l_2} = -\frac{1}{1 + \left(\frac{l_2}{l_1}\right)^2} \cdot \frac{1}{l_1} \left[\frac{l_1}{l_1}\right] = \frac{-l_1}{l_1^2 + l_2^2}, \quad \frac{\partial F_3}{\partial l_4} = 1$$

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$$\left. \begin{array}{l} l_1 = 10.1 \\ l_2 = 7.4 \\ l_3 = 12.5 \end{array} \right\} \sigma = 0.1$$

$$\left. \begin{array}{l} l_4 = 36.22 \\ l_5 = 53.73 \end{array} \right\} \sigma = 0.005 R$$

$$A = \begin{bmatrix} 2l_1^0 & 2l_2^0 & -2l_3^0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ \frac{l_2^0}{l_1^0 + l_2^0} & \frac{-l_1^0}{l_1^0 + l_2^0} & 0 & 1 & 0 \end{bmatrix}$$

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$$f = -F - A \cdot (l - l^0) \quad 16-3$$

$$f_{r,i} = \begin{bmatrix} -(l_1^2 + l_2^2 - l_3^2) \\ -(l_4 + l_5 - \frac{\pi}{2}) \\ -(l_4 - \tan^{-1}(\frac{l_2}{l_1})) \end{bmatrix} - A \cdot (l - l^0)$$

$$\Delta l \quad 1e-05 \quad 1e-09 \quad 1e-14$$

$$\begin{bmatrix} -.0074 \\ -.0075 \\ 0.100 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} -.6 \\ .5 \\ .8 \\ -.0018 \\ .0018 \end{bmatrix} \quad \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \quad \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

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$$\text{dist } \sigma = 0.1 \quad \sigma_0^2 = .01 \quad W_d = \frac{.01}{.01} = 1 \quad 16-4$$

$$\text{ang } \sigma = .005 \quad W_a = \frac{.01}{.000025} = 400$$

$$W = \begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & 1 & & \\ & & & 400 & \\ & & & & 400 \end{bmatrix}$$

$$A, f, W \Rightarrow \text{LS solution}$$

$$k = (AQA^T)^{-1} f$$

$$Q = W^{-1}$$

$$v = QA^T k$$

$$\underline{l+v} = \underline{l^0 + \Delta l}$$

$$\Delta = l - l^0 + v$$

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$$N = \begin{bmatrix} -.0074 \\ -.0075 \\ .0104 \\ 0 \\ 0 \end{bmatrix} \quad \sigma = 0.1 \quad \lambda = \begin{bmatrix} 10.0926 \\ 7.3925 \\ 12.5104 \\ 0.6322 \\ 0.9386 \end{bmatrix} \quad 16-5$$

Computing derivatives

1. analytically
2. numerical approximation
3. symbolic processing

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Symbolic (matlab)

16-6

$$S = 'atan(y/x)'$$

$$\text{diff}(S, 'y') \rightarrow \frac{\frac{x}{x}}{\underbrace{x \left(\frac{y^2}{x^2} + 1 \right)}_{\text{result}}} = \frac{x}{x^2 + y^2}$$

$$\text{diff}(S, 'x') \rightarrow \frac{-y}{x^2 \cdot \left(\frac{y^2}{x^2} + 1 \right)} = \frac{-y}{x^2 + y^2}$$

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numerical approximation $\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x}$ 16-7

$$\frac{df}{dx} \approx \frac{f(x+\Delta x) - f(x)}{\Delta x} \quad ; \quad \Delta x : \text{small number}$$

$$\frac{\partial f}{\partial x_i} = \lim_{\Delta x \rightarrow 0} \frac{f(x_1, x_2, \dots, x_i + \Delta x, \dots, x_n) - f(x_1, \dots, x_i)}{\Delta x}$$

$$\frac{\partial f}{\partial x_i} = \frac{f(x_1, \dots, x_i + \Delta x, \dots, x_n) - f(x_1, \dots, x_i)}{\Delta x}$$

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implement in matlab : put f into function m-file 16-8

dx: array (vector) of perturbation (Δx 's)

x; f

for i = 1:n

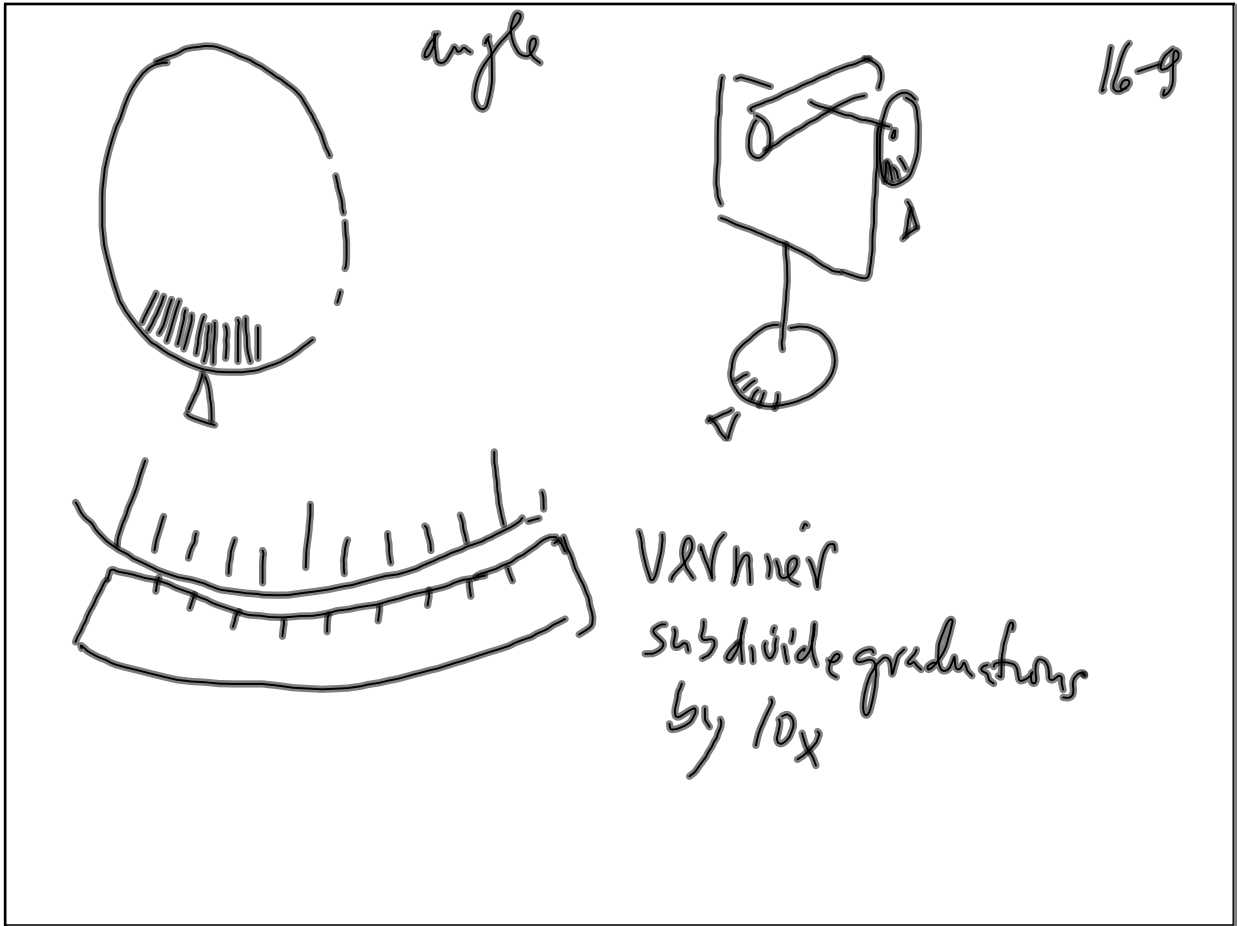
xx = x ;

xx(i) = xx(i) + dx(i)

→ $\frac{\partial f}{\partial x(i)} = \frac{f(xx) - f(x)}{dx(i)}$

end

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