

Error Propagation Law \vec{x}, Σ_{xx} 21-1

$\Sigma_{yy} = ?$ $\Rightarrow \vec{y} = A\vec{x}$ A : matrix of constants

$E(y) = E(Ax) = A E(x)$

$\rightarrow \mu_y = A \mu_x$

$\rightarrow \Sigma_{yy} = E\left\{ \underset{\substack{\uparrow \\ Ax}}{(y - \mu_y)} \underset{\substack{\uparrow \\ A\mu_x}}{(y - \mu_y)}^T \right\}$ defn. cov. μ_x .

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$\Sigma_{yy} = E\left\{ (Ax - A\mu_x)(Ax - A\mu_x)^T \right\}$ 21-2

$(x^T A^T - \mu_x^T A^T)$

$\Sigma_{yy} = E\left\{ A \underbrace{(x - \mu_x)}_{(x - \mu_x)^T} (x^T - \mu_x^T) A^T \right\}$

$\Sigma_{yy} = A E\left\{ (x - \mu_x)(x - \mu_x)^T \right\} A^T$

$\Sigma_{yy} = A \Sigma_{xx} A^T$ $y = Ax, \Sigma_{xx}$

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examples

$$y = a_1 x_1 + a_2 x_2$$

$$y = [a_1 \ a_2] \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\sigma_y^2 = [a_1 \ a_2] \begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$$\sigma_y^2 = a_1^2 \sigma_{x_1}^2 + a_2^2 \sigma_{x_2}^2 \quad \checkmark$$

$$\Sigma_{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}} = \begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix} \quad 21-3$$

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$$y = a_1 x_1 + a_2 x_2$$

$$y = [a_1 \ a_2] \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\Sigma_{xx} = \begin{pmatrix} \sigma_{x_1}^2 & \sigma_{x_1 x_2} \\ \sigma_{x_2 x_1} & \sigma_{x_2}^2 \end{pmatrix}$$

21-4

$$\sigma_y^2 = [a_1 \ a_2] \begin{pmatrix} \sigma_{x_1}^2 & \sigma_{x_1 x_2} \\ \sigma_{x_2 x_1} & \sigma_{x_2}^2 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$$\sigma_y^2 = a_1^2 \sigma_{x_1}^2 + \underline{\underline{2 a_1 a_2 \sigma_{x_1 x_2}}} + a_2^2 \sigma_{x_2}^2$$

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$$\begin{aligned}
 & \cdot y_1 = x_1 + 2x_2 \\
 & \cdot y_2 = 2x_1 + x_2 \\
 & \Sigma_{xx} = \begin{pmatrix} 4 & 1 \\ 1 & 4 \end{pmatrix} \quad z \leftarrow y \leftarrow X \quad \begin{matrix} \checkmark & \checkmark \\ & 2-5 \end{matrix} \\
 & z = \underline{y_1} + 2\underline{y_2} \quad \checkmark \quad z \leftarrow X
 \end{aligned}$$

$$z = x_1 + 2x_2 + 2(2x_1 + x_2) \quad \text{1-step}$$

$$z = 5x_1 + 4x_2$$

$$z = \begin{bmatrix} 5 & 4 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \quad \sigma_z^2 = \begin{bmatrix} 5 & 4 \end{bmatrix} \begin{pmatrix} 4 & 1 \\ 1 & 4 \end{pmatrix} \begin{pmatrix} 5 \\ 4 \end{pmatrix} = 204$$

$$\sigma_z = \sqrt{204}$$

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$$\begin{aligned}
 y_1 &= x_1 + 2x_2 \\
 y_2 &= 2x_1 + x_2 \\
 \Sigma_{xx} &= \begin{pmatrix} 4 & 1 \\ 1 & 4 \end{pmatrix} & \Sigma_{yy} &= A \Sigma_{xx} A^T \quad 2-6
 \end{aligned}$$

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \quad \Sigma_{yy} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 4 & 1 \\ 1 & 4 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 24 & 21 \\ 21 & 24 \end{pmatrix}$$

$$z = y_1 + 2y_2$$

Two-Step

$$z = \begin{bmatrix} 1 & 2 \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \quad \Sigma_{zz} = \sigma_z^2 = \begin{bmatrix} 1 & 2 \end{bmatrix} \begin{pmatrix} 24 & 21 \\ 21 & 24 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 204$$

$$\sigma_z^2 = 204, \quad \sigma_z = \sqrt{204} \quad \text{1 step \& 2 step yield}$$

SAME RESULT

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El for I/O LS method $\Sigma_{\delta\delta} = ?$ 21-7

$$\Delta = (B^T W B)^{-1} B^T W f \Rightarrow \Delta = [I \quad \Sigma_{\delta\delta}]$$

$$f = d - l = d - I l$$

$$f = -I l + d$$

$$Q_{ff} = (-I) Q_{ll} (-I)^T \quad y = Ax, \quad y = Ax + b$$

$$Q_{ff} = Q_{ll} \quad (Q = Q_{ll})$$

$$\Sigma = \sigma_0^2 Q$$

$$\Delta = [I \quad f]$$

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$$\Delta = (B^T W B)^{-1} B^T W f \quad Q_{ff} = Q \quad WQ = I \quad 21-8$$

$$Q_{\delta\delta} = (B^T W B)^{-1} B^T W \cdot Q \cdot [B^T W B]^{-1} B^T W$$

$$WB (B^T W B)^{-1} = I$$

$$Q_{\delta\delta} = (B^T W B)^{-1} = N^{-1} I$$

$$N \delta = t, \quad \delta = N^{-1} t$$

$$Q_{\delta\delta} = N^{-1}, \quad \Sigma_{\delta\delta} = \sigma_0^2 Q_{\delta\delta}$$

if $\sigma_0^2 = 1$
 then $\Sigma_{\delta\delta} = Q_{\delta\delta}$

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21-9

$$y = Ax + b \quad \Sigma_{yy} = A \Sigma_{xx} A^T$$

similar for linear & non-linear models

$$y = F(x)$$

$$y = F^0 + \frac{dF}{dx} \delta x$$

$$\underline{y = y^0 + J \delta x} \quad \Sigma_{yy} = J \Sigma_{xx} J^T$$

$$\Sigma = \sigma_0^2 Q \quad \Sigma_w = \tau_0^2 Q_w$$

$$\Sigma_{xx} = \sigma_0^2 Q_{xx} \quad \Sigma_{\hat{\theta}\hat{\theta}} = \sigma_0^2 Q_{\hat{\theta}\hat{\theta}}$$

$$\Sigma_{\delta\delta} = \sigma_0^2 Q_{\delta\delta}$$

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21-10

σ_0^2 $\sigma_0^2 / \sigma_i^2 = w_i$ prior

post

$$\hat{\sigma}_0^2 = \frac{v^T w v}{r}$$

↘

$$\left. \begin{aligned} \frac{(n-1) s^2}{\sigma^2} &\sim \chi_{n-1}^2 \\ \frac{r \cdot \hat{\sigma}_0^2}{\sigma_0^2} &\sim \chi_r^2 \end{aligned} \right\}$$

σ_0^2 : a priori ref. var.

$\hat{\sigma}_0^2$: a posteriori ref. var.

$$\frac{\chi \cdot \frac{v^T w v}{r}}{\sigma_0^2} = \frac{v^T w v}{\sigma_0^2} \sim \chi_r^2$$

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when you choose a value for σ_0^2 , think of it as choosing the observation (and variance) that will be assigned $w=1$. That choice is arbitrary. After adjustment, the correction to that observation might be much less or much greater than σ_0 . That indicates that our results are not consistent with assumptions. We will test this formally by comparing $\hat{\sigma}_0^2$ with σ_0^2 (post vs. prior): $r \cdot \hat{\sigma}_0^2 / \sigma_0^2 \sim \chi_r^2$

$$\hat{\sigma}_0^2 = \frac{v^T w v}{r} , \quad \boxed{\frac{v^T w v}{\sigma_0^2} \sim \chi_r^2} \quad \text{test statistic and distribution}$$

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