

$$r_{kk}(m=0) = \sum_{l=0}^{1022} c^k(l) c^k(l+m) = 1023 \quad 32-1$$

Acquisition

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32-2

1	2	3	...	10
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Sub frame

↑ HOW : TOW : time of transmission of next sub frame

ALMANAC				
1	2	3	4	5
	<u>EPH</u>	<u>EPH</u>	4-1 4-2 i	5-1 5-2 i

clock errors / status / health

30s

30s min. time for nav. solution

25 12.5 min broadcast ephemeris

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2 body problem

Ω : Right Ascension of asc. node

i : inclination

ω : argument of perigee

f : true anomaly

a : semi major axis

e : eccentricity

ECI system

GPS: ECF, Ω longitude of asc. node

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t_1 : transmit time \checkmark 32-4

t_2 : receive time \checkmark

$\Delta t = t_2 - t_1$ apparent travel time

$\sim 65 \text{ms}$

Pseudo Range $PR = c \cdot \Delta t$ $c: 3 \times 10^8 \text{ m/s}$

RINEX: receiver independent exchange format

unknowns: X, Y, Z recv. + 1 clock bias (per epoch)

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$$\begin{bmatrix} x \\ y \\ z \\ dt_1 \\ dt_2 \\ dt_3 \end{bmatrix} : B$$

$$PR_{CORR} = PR_{RAW} + c \cdot dt_s$$

$$PR_{CORR} = \left[\underline{(x_R - x_s)^2} + \underline{(y_R - y_s)^2} + \underline{(z_R - z_s)^2} \right]^{1/2} + c \cdot dt_R$$

$$F = PR_{CORR} - \left[\underline{(x_R - x_s)^2} + \underline{(y_R - y_s)^2} + \underline{(z_R - z_s)^2} \right]^{1/2} - c \cdot dt_R$$

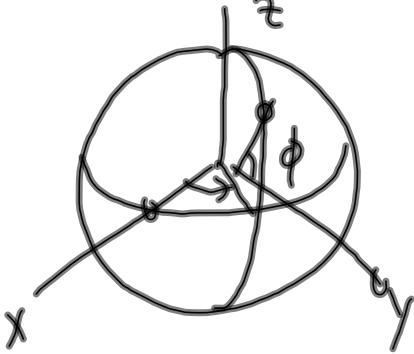
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Recommend: units km, μsec

formats of data files: RINEX $\left\{ \begin{array}{l} \text{stat. pos.} \dots \\ \text{observations} \dots \end{array} \right.$

to exclude observations too close to horizon:



λ longitude
 ϕ latitude
 h ellipsoid

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \leftrightarrow \begin{pmatrix} \phi \\ \lambda \\ h \end{pmatrix}$$

↓

local cartesian - (e, n, u)

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$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} (N+h) \cos \phi \cos \lambda \\ (N+h) \cos \phi \sin \lambda \\ ((1-e^2)N+h) \sin \phi \end{pmatrix}$$

N : radius of Curvature
prime vert

$$N = a / (1 - e^2 \sin^2 \phi)^{1/2}$$

other directions: iterate

- o approx ϕ , get N
- o $h = \frac{(x^2 + y^2)^{1/2}}{\cos \phi} - N$
- o $\phi = \tan^{-1} \left[\frac{z}{(x^2 + y^2)^{1/2} (1 - e^2 (\frac{N}{N+h}))^{-1}} \right]$
- o $\lambda = \tan^{-1}(y/x)$ * use 2 argument version

repeat until
no change

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$$\begin{pmatrix} e \\ h \\ n \end{pmatrix} = M_x(90^\circ - \phi) M_z(\lambda + 90^\circ) \left[\begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} \right]$$

↑
ref. point

↑
elev. angle
exclude $< 5^\circ, 10^\circ, 15^\circ$

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