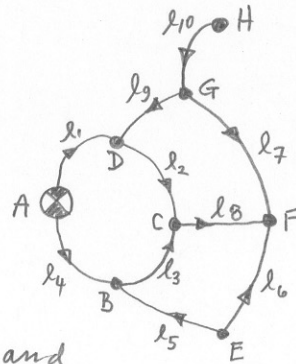
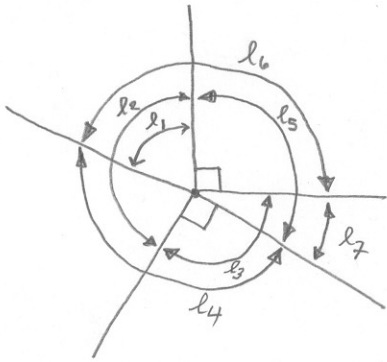


YOU ARE ALLOWED ONE 8½" x 11" PAGE OF NOTES (BOTH SIDES)

1. Find n , n_0 , and r in the level network shown in the sketch. Point A has a known, fixed height.



2.



Analyze the angle figure and determine n , n_0 , r . Note that two of the angles shown are fixed at 90° . Write condition equations in matrix form as

$$(1) \quad V + B\Delta = f$$

$$(2) \quad Av = f$$

3. Given the following equations,

$$Y_1 = X_1 + 3X_3$$

$$Y_2 = 2X_1 - X_2 - 2X_3$$

$$\Sigma_{XX} = \begin{bmatrix} \sigma_{X_1}^2 & \sigma_{X_1 X_2} & \sigma_{X_1 X_3} \\ \sigma_{X_2 X_1} & \sigma_{X_2}^2 & \sigma_{X_2 X_3} \\ \sigma_{X_3 X_1} & \sigma_{X_3 X_2} & \sigma_{X_3}^2 \end{bmatrix} = \begin{bmatrix} 3 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

what is Σ_{YY} ?

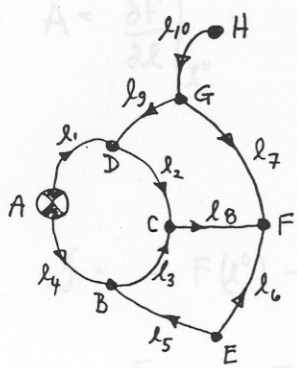
what is the correlation coefficient $r_{Y_1 Y_2}$?

4. Show the linearized form of the following condition equation as $Av = f$ using the given values for the original observations, l , and the refined observations, l° .

$$F(\hat{l}) = \hat{l}_1 \sin \hat{l}_2 - \hat{l}_3 \hat{l}_4^2 = 0$$

$$l = \begin{bmatrix} 100.2 \\ 30.2 \text{ deg.} \\ 0.52 \\ 9.8 \end{bmatrix}, \quad l^\circ = \begin{bmatrix} 100.1 \\ 30.1 \text{ deg.} \\ 0.51 \\ 9.9 \end{bmatrix}$$

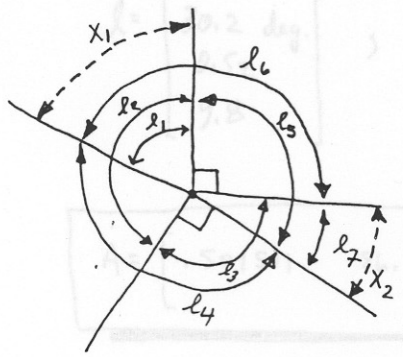
1.



$$n = 10$$

$$\frac{n_o}{r} = \frac{7}{3}$$

2.



parameters selected x_1, x_2

$$n = 7$$

$$\frac{n_o}{r} = \frac{2}{5}$$

(1) $Av = f$

1. $\hat{l}_6 = \hat{l}_1 + 90^\circ$, $\hat{l}_1 - \hat{l}_6 = -90^\circ$
2. $\hat{l}_3 = \hat{l}_7 + 90^\circ$, $\hat{l}_3 - \hat{l}_7 = 90^\circ$
3. $\hat{l}_5 - \hat{l}_7 = 90^\circ$, $\hat{l}_5 - \hat{l}_7 = 90^\circ$
4. $\hat{l}_2 + \hat{l}_5 + 90^\circ = 0$, $\hat{l}_2 + \hat{l}_5 = -90^\circ$
5. $\hat{l}_4 + \hat{l}_6 + \hat{l}_7 = 360^\circ$, $\hat{l}_4 + \hat{l}_6 + \hat{l}_7 = 360^\circ$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ v_6 \\ v_7 \end{bmatrix} = \begin{bmatrix} -90^\circ \\ 90^\circ \\ 90^\circ \\ -90^\circ \\ 360^\circ \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \\ l_3 \\ l_4 \\ l_5 \\ l_6 \\ l_7 \end{bmatrix}$$

$$A \cdot v = \underbrace{d}_{f} - \underbrace{A \cdot e}_{f}$$

$$l_1 + v_1 = x_1 \quad , \quad v_1 - x_1 = -l_1$$

$$l_2 + v_2 = 360^\circ - 180^\circ - x_2 \quad , \quad v_2 + x_2 = 180^\circ - l_2$$

$$l_3 + v_3 = 90^\circ + x_2 \quad , \quad v_3 - x_2 = 90^\circ - l_3$$

$$l_4 + v_4 = 360^\circ - 90^\circ - x_1 - x_2 \quad , \quad v_4 + x_1 + x_2 = 270^\circ - l_4$$

$$l_5 + v_5 = 90^\circ + x_2 \quad , \quad v_5 - x_2 = 90^\circ - l_5$$

$$l_6 + v_6 = 90^\circ + x_1 \quad , \quad v_6 - x_1 = 90^\circ - l_6$$

$$l_7 + v_7 = x_2 \quad , \quad v_7 - x_2 = -l_7$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ v_6 \\ v_7 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & 1 \\ 0 & -1 \\ 1 & 1 \\ 0 & -1 \\ -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 180^\circ \\ 90^\circ \\ 270^\circ \\ 90^\circ \\ 90^\circ \\ 0 \end{bmatrix} - \begin{bmatrix} l_1 \\ l_2 \\ l_3 \\ l_4 \\ l_5 \\ l_6 \\ l_7 \end{bmatrix}$$

$$v + B \cdot \Delta = \underbrace{d}_{f} - \underbrace{e}_{f}$$

3. $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 3 \\ 2 & -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$, $\Sigma \gamma \gamma = A \Sigma_{xx} A^T = \begin{bmatrix} 1 & 0 & 3 \\ 2 & -1 & -2 \end{bmatrix} \begin{bmatrix} 3 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \\ 3 & -2 \end{bmatrix} =$

$$\Sigma \gamma \gamma = \begin{bmatrix} 21 & -10 \\ -10 & 22 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 4 & 6 \\ 5 & -2 & -5 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \\ 3 & -2 \end{bmatrix} = \begin{bmatrix} 21 & -10 \\ -10 & 22 \end{bmatrix}$$

$$\sigma_{y_1 y_2} = \frac{\sigma_{x_1 x_2}}{\sigma_{x_1} \sigma_{x_2}} = \frac{-10}{(4.582)(4.690)} = \underline{\underline{-.465}}$$

$$4. \quad A = \left. \frac{\partial F}{\partial l} \right|_{l^0} : \begin{bmatrix} \frac{\partial F}{\partial l_1} & \frac{\partial F}{\partial l_2} & \frac{\partial F}{\partial l_3} & \frac{\partial F}{\partial l_4} \end{bmatrix}$$

$$\boxed{F(l) = \hat{l}_1 \sin \hat{l}_2 - \hat{l}_3 \hat{l}_4^2 = 0}$$

$$\left[\sin l_2 \quad l_1 \cos l_2 \quad -l_4^2 \quad -2l_3 l_4 \right] \Big|_{l^0}$$

$$f = -F(l^0) - A(l-l^0)$$

$$l = \begin{bmatrix} 100.2 \\ 30.2 \text{ deg.} \\ 0.52 \\ 9.8 \end{bmatrix}, \quad l^0 = \begin{bmatrix} 100.1 \\ 30.1 \\ 0.51 \\ 9.9 \end{bmatrix}, \quad l-l^0 = \begin{bmatrix} 0.1 \\ 0.1 \text{ deg} \\ 0.01 \\ -0.1 \end{bmatrix} = \begin{bmatrix} 0.1 \\ 0.001745 \text{ Rad} \\ 0.01 \\ -0.1 \end{bmatrix}$$

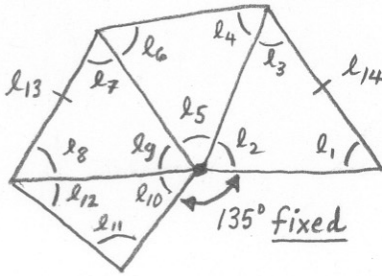
$$\boxed{A = \begin{bmatrix} .501511 & 86.601657 & -98.01 & -10.098 \end{bmatrix}}$$

$$f = - \left[(100.1) \sin(30.1^\circ) - (0.51)(9.9)^2 \right] - \begin{bmatrix} .501511 & 86.601657 & -98.01 & -10.098 \end{bmatrix} \begin{bmatrix} 0.1 \\ .001745 \text{ R} \\ .01 \\ -0.1 \end{bmatrix}$$

$$f = \left[-0.216125 \quad - \quad .230971 \right]$$

$$\boxed{f = -.447096}$$

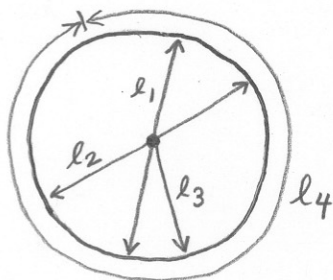
1. The size and shape of the figure are the model. Give n , n_0 , and r .



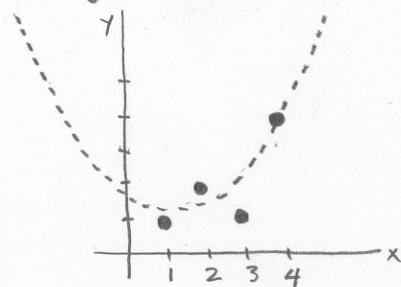
2.
$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a & b \\ -b & a \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix}$$
 relates coordinates (x,y) , coordinates (X,Y) , and transformation parameters (a,b) .

If $(X,Y) = (1,1)$ are constants, and if $\Sigma \begin{pmatrix} a \\ b \end{pmatrix} = \begin{bmatrix} \sigma_a^2 & \sigma_{ab} \\ \sigma_{ab} & \sigma_b^2 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$,
What is $\Sigma \begin{pmatrix} x \\ y \end{pmatrix}$?

3. The size of a circle is the model. Observed are 2 diameters l_1, l_2 , a radius, l_3 , and a circumference l_4 . Write the condition equations for adjustment of observations only, in matrix form, $Av = f$

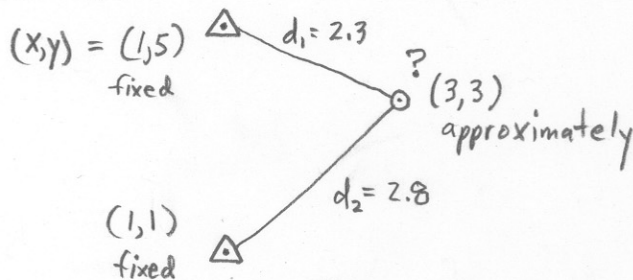


4. You wish to fit a parabola of the form $y = a_0 + a_1x + a_2x^2$ to the following data. X 's are constant, y 's are observations. Write condition equations for adjustment of indirect observations in matrix form, $V + B\Delta = f$. What is an appropriate weight matrix?

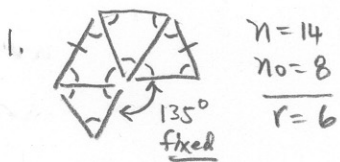


X	Y	σ_y
1	1	3
2	2	2
3	1	1
4	4	1

5. Two distance observations are made from two fixed points to an unknown point. Write condition equations to solve for coordinates of the unknown point by least squares, indirect observations, in matrix form, $V + B\Delta = f$.



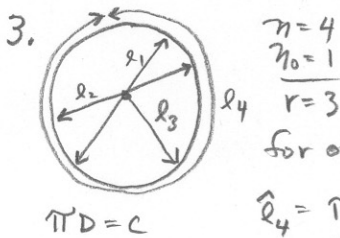
CE 506 Exam I - Solution



2. $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ -b & a \end{pmatrix} \begin{pmatrix} X \\ Y \end{pmatrix}$ must be in form $Y = AX$
 constant matrix \uparrow random vector with known cov. matrix

$\begin{pmatrix} X \\ Y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, $x = a \cdot 1 + b \cdot 1$
 $y = -b \cdot 1 + a \cdot 1$, $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}$ That's what we need

$\Sigma_{\begin{pmatrix} x \\ y \end{pmatrix}} = A \Sigma_{\begin{pmatrix} a \\ b \end{pmatrix}} A^T$, $\Sigma_{\begin{pmatrix} x \\ y \end{pmatrix}} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 6 & 0 \\ 0 & 2 \end{pmatrix}$



for observations only, need $c=r=3$ condition equations

$\hat{l}_4 = \pi \hat{l}_1$ $\pi \hat{l}_1 - \hat{l}_4 = 0$ $\pi(l_1 + v_1) - l_4 - v_4 = 0$ $\pi v_1 - v_4 = -\pi l_1 + l_4$
 $\hat{l}_1 = \hat{l}_2$ $\hat{l}_1 - \hat{l}_2 = 0$ $l_1 + v_1 - l_2 - v_2 = 0$ $v_1 - v_2 = -l_1 + l_2$
 $\hat{l}_3 = \frac{1}{2} \hat{l}_1$ $\frac{1}{2} \hat{l}_1 - \hat{l}_3 = 0$ $\frac{1}{2}(l_1 + v_1) - l_3 - v_3 = 0$ $0.5v_1 - v_3 = -0.5l_1 + l_3$

$$\begin{bmatrix} \pi & 0 & 0 & -1 \\ 1 & -1 & 0 & 0 \\ 0.5 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = - \begin{bmatrix} \pi & 0 & 0 & -1 \\ 1 & -1 & 0 & 0 \\ 0.5 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \\ l_3 \\ l_4 \end{bmatrix}$$

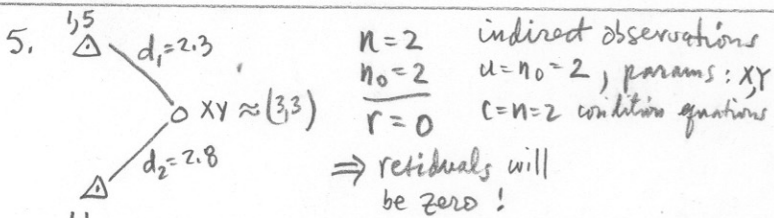
$A \quad v = \quad f$

4. $y = a_0 + a_1 x + a_2 x^2$ $n=4$ $v_1 - a_0 - a_1(1) - a_2(1^2) = -1$ $\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} + \begin{bmatrix} -1 & -1 & -1 \\ -1 & -2 & -4 \\ -1 & -3 & -9 \\ -1 & -4 & -16 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -1 \\ -2 \\ -1 \\ -4 \end{bmatrix}$
 $y + v_y - a_0 - a_1 x - a_2 x^2 = \phi$ $n_0=3$ $v_2 - a_0 - a_1(2) - a_2(2^2) = -2$
 $v_3 - a_0 - a_1(3) - a_2(3^2) = -1$
 $v_4 - a_0 - a_1(4) - a_2(4^2) = -4$ $r=1$

$v_4 - a_0 - a_1 x - a_2 x^2 = -y$

$$W = \begin{bmatrix} 1/3^2 & & & \\ & 1/2^2 & & \\ & & 1/1^2 & \\ & & & 1/2^2 \end{bmatrix} = \begin{bmatrix} 1/9 & 0 & 0 & 0 \\ 0 & 1/4 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$v + B \quad \Delta = f$



$d_1 = [(x-1)^2 + (y-5)^2]^{1/2}$
 $d_2 = [(x-1)^2 + (y-1)^2]^{1/2}$

$F_1 = d_1 - [(x-1)^2 + (y-5)^2]^{1/2} = 0$ $\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} \partial F_1 / \partial x & \partial F_1 / \partial y \\ \partial F_2 / \partial x & \partial F_2 / \partial y \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix} = \begin{bmatrix} -F_1^0 \\ -F_2^0 \end{bmatrix}$ evaluated at $x^0, y^0 = 3, 3$
 $F_2 = d_2 - [(x-1)^2 + (y-1)^2]^{1/2} = 0$

$\frac{\partial F_1}{\partial x} = -\frac{1}{2} []^{-1/2} \cdot 2(x-1) = -0.707$, $\frac{\partial F_1}{\partial y} = -\frac{1}{2} []^{-1/2} \cdot 2(y-5) = +0.707$, $F_1^0 = -0.52$
 $\frac{\partial F_2}{\partial x} = -\frac{1}{2} []^{-1/2} \cdot 2(x-1) = -0.707$, $\frac{\partial F_2}{\partial y} = -\frac{1}{2} []^{-1/2} \cdot 2(y-1) = -0.707$, $F_2^0 = -0.03$

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} -0.707 & 0.707 \\ -0.707 & -0.707 \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix} = \begin{bmatrix} 0.52 \\ 0.03 \end{bmatrix}$$

$v + B \quad \Delta = f$