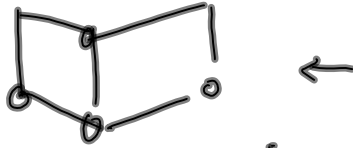


HWS :



26-1

1 set of 4 pts. visible on each photo
initial approximations $E_0 (x_i, y_i, z_i, w_i, k)$



2nd set of points for "control" or minimal
widest possible baseline constraints

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1cm meas. error : 1m object
1% meas error

26-2

1cm meas error : 10m length
0.1% meas error

you could use points from group 2 for
approx E_0 ,

do not use points from group 1 for control

I must post bld-geom.m
└ point-list.txt, quad.s.txt

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Matching or Correspondence problem

26.3

CC : workhorse tool for
similarity metric NCC $-1 \rightarrow +1$
cross correlation

LSM : refinement to subpixel accuracy
least squares matching
cond. equation $I_{int_1} = I_{int_2}$
parameters : shift x , shift y , rotation, scale

leads to : automated approach to
tie point selection

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after LSM : estimated d_x, d_y

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$$\sum \begin{pmatrix} d_x \\ d_y \end{pmatrix} : \lambda_1, \lambda_2$$

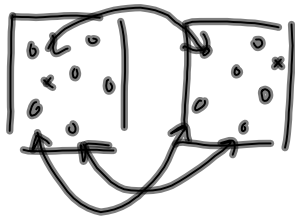
λ_1, λ_2 : small + approx equal

\Rightarrow compute $\sum \begin{pmatrix} d_x \\ d_y \end{pmatrix}$
look for λ 's small + equal

\Rightarrow Interest Points (corner detector)

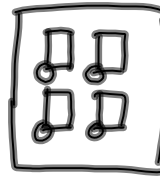


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I.P.

26-5



determino conjugates:

IP + CC + RANSAC
(random sample consensus)

select @ random 5 pts 1, corresp. 2

get R0 parameters inliers

Choose the one with most inliers

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$$CC: \sigma_x^2 = E\{(x - \mu_x)^2\}$$

$$\sigma_y^2 = E\{(y - \mu_y)^2\}$$

$$\sigma_{xy} = E\{(x - \mu_x)(y - \mu_y)\}$$

population values

$$\Sigma = \begin{bmatrix} \sigma_x^2 & \sigma_{xy} \\ \sigma_{xy} & \sigma_y^2 \end{bmatrix}$$

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$$\rho_{xy} = \frac{\sigma_{xy}}{\sigma_x \sigma_y}$$

-1 → +1

ρ standardized, normalized covariance

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Sample : sample cov. matrix

26-7

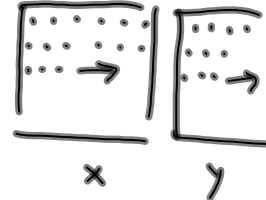
$$\begin{bmatrix} S_x^2 & S_{xy} \\ S_{yx} & S_y^2 \end{bmatrix} = \sum_{\text{sample}} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$S_x = \sqrt{\frac{\sum (x_i - \bar{x})^2}{N-1}}$$

$$S_y = \sqrt{\frac{\sum (y_i - \bar{y})^2}{N-1}}$$

$$S_{xy} = \frac{1}{N-1} \sum (x_i - \bar{x})(y_i - \bar{y})$$

$$r_{xy} = \text{sample c.c.} \quad \boxed{\frac{S_{xy}}{S_x S_y}}$$



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$$r_{xy} = \frac{1}{N-1} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$$

26-8

$$\sqrt{\left[\frac{1}{N-1} \sum (x_i - \bar{x})^2 \right] \left[\frac{1}{N-1} \sum (y_i - \bar{y})^2 \right]}$$

$$r_{xy} = \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\left[\sum (x_i - \bar{x})^2 \sum (y_i - \bar{y})^2 \right]^{1/2}} \quad \text{Sample cov. coeff.}$$

Normalized C.C.

$$x_i, y_i \quad \mu_i, \nu_i \quad \begin{array}{l} x: \text{image 1} \\ y: \text{image 2} \end{array}$$

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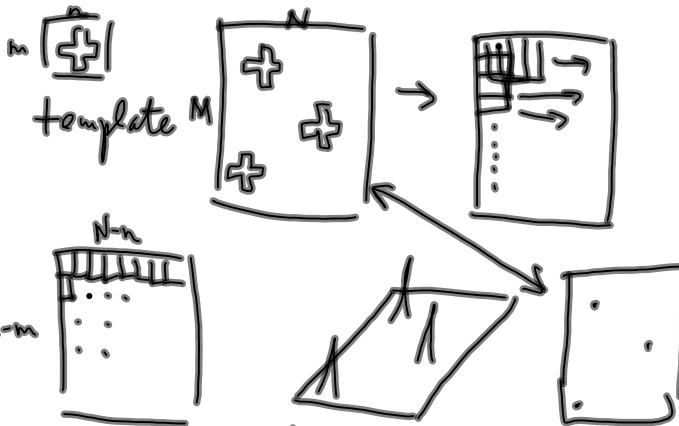
app's for cc

26-9

- photogrammetry :
1. signalized pt. detection
 2. terrain extraction (surface)
 3. detect conjugates IP

- elsewhere :
1. GPS acquisition
 2. Radar matched filter

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26-10

look through response map
look for values exceed
threshold

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