

Spaceborne Imaging Systems - Homework 2

1/3

assigned Thurs 19 Feb 2009, due Tuesday March 3

see additional comments at end

1. find support data for QuickBird (Digital Globe) image in dg-meta.zip in ftp.ecn.purdue.edu/bethel.
2. in the file dg.eph locate ephemeris points numbered: 400, 450, 500.
3. Using algorithms discussed in class convert each ECF state vector to ECI reference frame, then convert the ECI state vectors to Kepler elements
4. compare a (\neq computed altitude), i , e to published values.
5. Between #400 \rightarrow #450, and #450 \rightarrow #500 compute \dot{r} , \dot{w} , \dot{i} , \dot{a} , \dot{e} , $\dot{\Omega}$. which ones seem significant?

note: you are free to look at solution to similar problem from 2008 and use any code provided:

qb-eci-ecf.m, precession.m, nutation.m, iau1980n.txt, jd.m, kep2stv.m, stkp6.m

6. using above developed software tools, plot the subsequent orbit path for 1 day @ 1 minute intervals using the following algorithm:

- (a) take the Kepler elements for eph. point #400 as the base point.

(b) advance the time by 1 minute 2/3

$$M = n(t - t_p) \quad t_p = \text{time @ perigee}$$

(c) using the "new" Kepler elements, convert to state vectors in ECI reference frame

(d) with the new time, approximate new R by $R = T_{\text{constant}} \Theta_{\text{approx}} N_{\text{constant}} P_{\text{constant}}$ where,

$$\Theta_{\text{approx}} = R_3(\text{GAST}')^1$$

$$\text{GAST}' = \text{GAST}_0 + \left(\frac{\# \text{min}}{1440} \right) \cdot 2\pi \cdot \frac{366.25}{365.25}$$

(Solar minutes to sidereal angle!)

(e) using new R convert X_{ECI} to X_{ECF} (position only)

(f) scale X_{ECF} to surface of earth

(g) convert XYZ_{ECF} to geographic ϕ, λ, h , save in a trajectory array ϕ_i, λ_i

(h) plot base map and trajectory points (matlab) by:

- load coast

- plot (long, lat, 'b-') (decimal degrees)

This is just raw ϕ, λ a "platte carre" projection^{3/3}

- plot a trajectory data point (decimal degrees)

`plot($\lambda_i, \phi_i, 'r.'$)`

if ($\phi_i < 70$ deg) and (on descending path)

$$\phi_i < \phi_{i-1}$$

descending path = daytime

ascending path = nighttime

- Careful about units m, km, radians, degrees
time seconds, arc seconds,
- can use code from 2008 but you are encouraged
to write your own — (you learn more!)
- path should start @ West Lafayette IN !

1. During the course of one day, the satellite will make ~14 orbits, so each time that $(t - t_p)$ exceeds τ , the period, then you need to update $t_p = t_p + \tau$, so that M stays in the range $0 \rightarrow 2\pi$