

```
version = "22.0";
generationTime = 2009-09-21T17:26:29.000000Z;
productOrderId = "052224881010_01_P001";
productCatalogId = "2020010049CE3E00";
imageDescriptor = "Basic1B";
bandId = "P";
panSharpenAlgorithm = "None";
numRows = 28816;
numColumns = 34877;
productLevel = "LV1B";
productType = "Basic";
numberOfLooks = 1;
radiometricLevel = "Corrected";
bitsPerPixel = 16;
compressionType = "None";
BEGIN_GROUP = BAND_P
    ULLon = -86.98916944;
    ULLat = 40.50078932;
    ULHAE = 183.70;
    URLon = -86.77531942;
    URLat = 40.50353757;
    URHAE = 163.59;
    LRLon = -86.77522155;
    LRLat = 40.36998083;
    LRHAE = 172.00;
    LLLon = -86.98917948;
    LLLat = 40.36699577;
    LLHAE = 151.73;
    absCalFactor = 6.243908e-02;
    effectiveBandwidth = 3.720000e-01;
    TDILevel = 16;
END_GROUP = BAND_P
outputFormat = "GeoTIFF";
BEGIN_GROUP = IMAGE_1
    satId = "WV01";
    mode = "FullSwath";
    scanDirection = "Forward";
    CatId = "1020010003A9A600";
    TLCTime = 2008-07-01T16:44:36.622625Z;
    numTLC = 2;
    TLCList = (
        (0, 0.000000),
        (28816, 2.422333) );
    firstLineTime = 2008-07-01T16:44:36.622625Z;
    avgLineRate = 11895.97;
    exposureDuration = 0.00134499;
    minCollectedRowGSD = 0.510;
    maxCollectedRowGSD = 0.511;
    meanCollectedRowGSD = 0.511;
    minCollectedColGSD = 0.517;
    maxCollectedColGSD = 0.519;
    meanCollectedColGSD = 0.518;
    meanCollectedGSD = 0.514;
    meanProductRowGSD = 0.515;
    meanProductColGSD = 0.521;
    meanProductGSD = 0.518;
    rowUncertainty = 24.36;
    colUncertainty = 26.50;
    minSunAz = 135.5;
    maxSunAz = 135.7;
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meanSunAz = 135.6;
minSunEl = 67.7;
maxSunEl = 67.8;
meanSunEl = 67.8;
minSatAz = 228.4;
maxSatAz = 235.4;
meanSatAz = 231.4;
minSatEl = 78.3;
maxSatEl = 79.9;
meanSatEl = 79.0;
minInTrackViewAngle = -7.5;
maxInTrackViewAngle = -7.2;
meanInTrackViewAngle = -7.4;
minCrossTrackViewAngle = -6.9;
maxCrossTrackViewAngle = -6.5;
meanCrossTrackViewAngle = -6.7;
minOffNadirViewAngle = 10.0;
maxOffNadirViewAngle = 10.0;
meanOffNadirViewAngle = 10.0;
PNIIRS = 5.2;
cloudCover = 0.008;
resamplingKernel = "CC";
positionKnowledgeSrc = "R";
attitudeKnowledgeSrc = "R";
revNumber = 4369;
END_GROUP = IMAGE_1
END;□
```