#### On the Designs and Challenges of Practical Binary Dirty Paper Coding

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## Introduction



- Why dirty paper coding (DPC)?
  - Eliminating inter-user interference (IUI)
  - Alternative approach: linear processing (away from the capacity)
  - Costa's proof (Costa '83)
  - Footstone of theoretical studies of the Gaussian MIMO broadcast channel (Caire *et al.* '03)



# General Framework of Binary DPC

- ✤ DPC encoder sends the transmitted signal x, a function f(d,s) of the interference s and information data d
  ♦ y = x + s + n
- \* The goal of DPC is to optimize the transmission rate R subject to a normalized power constraint W on x.



## Achieving DPC capacity: Random binning

Noncausal side information (Gel'fand and Pinsker '80)  $C = \max_{p(u,x|s)} [I(U;Y) - I(U;S)].$ 

• Generate  $2^{N(I(U;Y)-\delta)}$  sequences, divide these into  $2^{NR}$  bins

- ✤ *R* is chosen to be less than  $I(U;Y) I(U;S) \varepsilon$ , each bin has  $2^{N(I(U;S) \varepsilon')}$  sequences
- \* Encoder finds a sequence u which is the closest to s based on d and sends x which is a function of u and s.

 Decoder looks for a sequence u 
 s.t. u and y are the closest and identifies the bin which includes u.





# Coset-based binning

- \*  $C_0$ ,  $C_1$ : the quantization code and the information bearing code
- ♦ *d* is mapped to  $c_1$ ,  $c_1 + C_0$  forms a coset (a bin)
- Siven *s*, the encoder finds  $c_0$  such that  $c_1 + c_0$  in the  $c_1 + C_0$  bin is the closest to *s*
- The transmitted signal x is  $c_0 + c_1 s$
- The decoder finds  $c_0$  and  $c_1$  such that  $c_0 + c_1$  is the closest to y.
- ✤ For a practical implementation, if  $c_0$  and  $c_1$  are uniform, then no bit-based message-passing decoder can extract any information from  $c_0 + c_1$





#### Superpostion-coding-based (Bennatan et al. '06)

\* Either  $c_0$  or  $c_1$  has non-uniform a priori distribution to initialize iterative decoding

- Nonbinary low-density parity-check (LDPC) codes
  - > The normalized Hamming weight  $\sigma$  of  $c_1$
  - ► GF(q) LDPC code can only achieve  $\sigma = \frac{1}{a}, \frac{2}{a}, \dots, \frac{(q-1)}{a}$
- Symbol mapper a nonlinear code



The proposed system

Coset-based binning
 Initialization problem

Edge erasing with binary LDPC codes to initialize iterative decoding



Code optimization

Density evolution (DE), the extrinsic information transfer (EXIT) chart





# System model

- Random interleaver to reduce the dependence
- $\diamond$   $c_1$  is punctured by *e* and is padded with zeros.
- Viterbi decoder chooses  $c_0$  such that  $c_0 + (c_1)_p$  is closest to S

♦ 
$$y = x + s + n = c_0 + (c_1)_p + n$$





# Decoding in the Factor Graph

- ❖ Iterative decoding between the BCJR and LDPC decoders
   ❖ Set LLR values at punctured positions using y = c₀ + n
   ➢ BCJR decoder Log MAP
- After BCJR decoding, the extrinsic information in the Information non-punctured part is delivered to LDPC decoder.
- LDPC decoding is performed with the received bits and the extrinsic LLR information
- Continue iterative decoding





#### System parameters

Solution  $\diamond$  BSC with *p* and weight constraint *W* are given and design parameters are  $R_0$  and  $R_1$ 

	The proposed scheme	Superposition (Bennatan et al.)
$R_0$ and $R_1$	$R_0 > 1 - h(W), R_1 < h(W) - h(p)$	
W and p	No constraint	$W = \sigma(1-p) + p(1-\sigma)$
q	No constraint	$\sigma = 1/q$ to $(q-1)/q$

- To flexibly support different W values, very high-order GF(q) has to be used increases complexity
- Our system is flexible and can easily handle different weight constraints W using *edge erasing* and *binary* LDPC codes.



# Code optimization

#### The EXIT chart

- > Use oL and iL as the input and the output
- Assuming *oL* (*iL* resp.) is always Gaussian distributed input with mean and variance (μ , 2μ) for BCJR (LDPC)
- The mutual information of the output LLR messages is obtained by

$$I(X;Y) = h(X) - h(X | Y) = 1 - h(X | Y)$$

$$=1-\int_{-\infty}^{+\infty}\log_{2}\frac{e^{m}+1}{e^{m}}P(m \mid X=0)dm$$

where *m* denotes the LLR messages, that is,  $m = \frac{\log_2(Y \mid X = 0)}{\log_2(Y \mid X = 1)}$ 



#### How to choose e

- **\*** Estimate the threshold  $p^*$ 
  - > By selecting the largest p value two curves do not cross each other
- Optimize the e value
  - > Given  $p^*$ , choose an *e* value the two curves are the farthest apart

• Optimize  $p^*$  and *e* iteratively





#### Code design for LDPC code

- The joint use of DE and the EXIT chart
- **\diamond** Record the distributions of *iL*, use the pmfs as an input of DE
- \* Perform DE iterations, obtain the distribution of oL
- By computing the mutual information of *oL*, use the EXIT curve of BCJR to find the pmf of *iL*
- Given a degree distribution, Parity check whether the EXIT curve and DE converge
   Differential Evolution





# Trajectory of Monte Carlo Simulation

- Record the LLR distributions under real BCJR+LDPC decoding and convert them to the mutual information
- The zigzag trajectory fits the two EXIT curves well
- Sy choosing different numbers of LDPC iterations in the initial and final stages,

we can control the total number of LDPC iterations to be roughly 100-150

How many outer loop iteration?





#### Simulation and Discussions

♦ Quasi-cyclic LDPC codes ( R<sub>1</sub> = 0.36, N = 10<sup>5</sup> )
> 200×272 base matrix
> λ(x) = 0.53x + 0.21x<sup>2</sup> + 0.01x<sup>3</sup> + 0.25x<sup>9</sup>, ρ(x) = 0.2x<sup>2</sup> + 0.8x<sup>3</sup>
♦ Convolutional code ( R<sub>0</sub> = 1/8 ) (2565, 2747, 3311, 3723, 2373, 2675, 3271, 2473)

- Performance  $p^* = 0.097 \text{ vs } p^* = 0.1$
- Our scheme have several advantages – complexity, flexibility, and efficient encoding and decoding.





#### Conclusion

- Practical scheme for binary dirty-paper channels based on random binning
- Binary LDPC codes and edge erasing the advantages for complexity.
- Choose system parameters flexibly important in the practical system.
- Code design combining EXIT chart and DE jointly
- Similar performance to that of state-of-the-art superposition-coding-based binary DPC scheme.
- Future research Extend to Gaussian DPC



