

# Practical Issues in Designing and Conducting an AI Experiment

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## Five Issues to be Considered

- Range of stimulus parameter ( $R$ )
- Number of stimulus alternatives ( $k$ )
- Spacing between the  $k$  stimuli (*linear vs. log*)
- Total number of trials ( $n$ )
- Training procedure

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## Issue #1: Range of Stimulus Parameter ( $R$ )

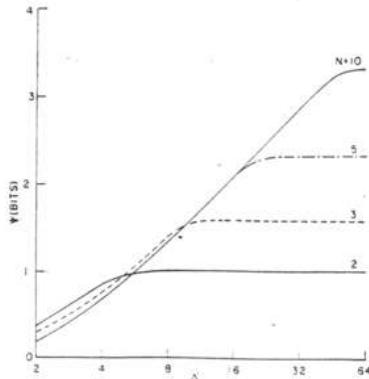


FIG. 1. Dependence of mutual information  $\Psi$  on the total sensitivity  $\Delta'$  for various values of the number  $N$  of stimuli. (See text for assumptions.)

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### ■ Problem

- ◆ At small  $R$ , where  $R=\log(I_{\max}/I_{\min})$ , information transfer < channel capacity

### ■ Strategy

- ◆ Use largest possible range given the experimental setup

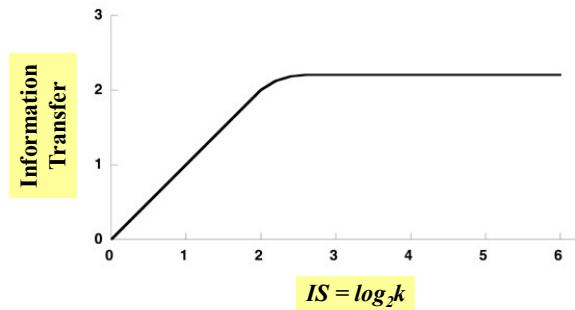
### ■ Examples of “largest possible range”

- ◆ Sound levels: AL to “too loud”
- ◆ Curvature: straight line to arc of the smallest circle that can be drawn
- ◆ Weight: AL to “too heavy”

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## Issue #2: Number of Stimulus Alternatives ( $k$ )

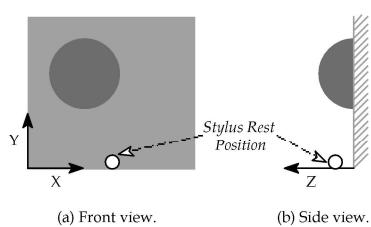
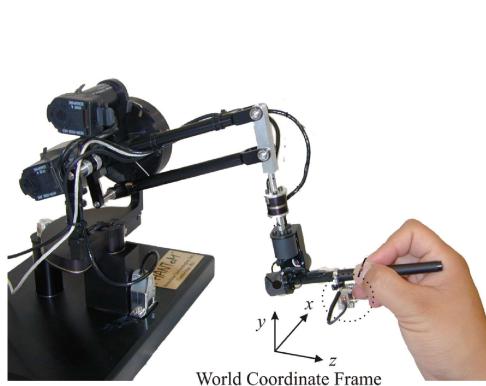


- Small  $k$  limits  $IT_{est}$
- Large  $k$  requires too many trials
- One strategy: increase  $k$  until  $IT_{est}$  asymptotes

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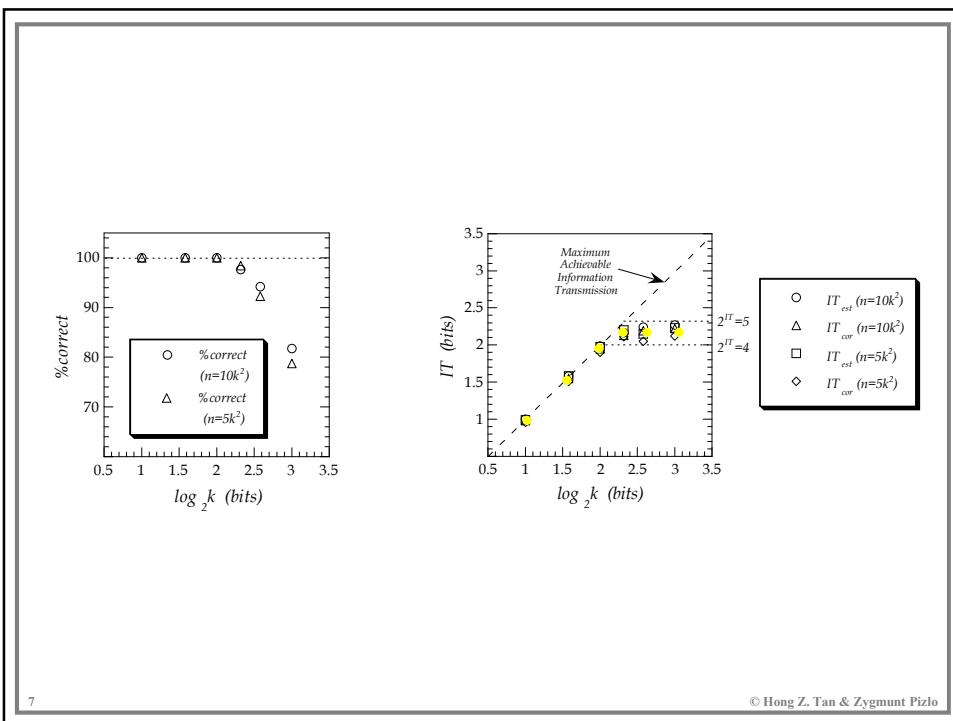
## An Example (Tan, 1997)



**Range of radius:**  
**10 – 80 mm**  
**For different numbers**  
**Of stimulus alternatives (k)**

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## Issue #3: *Linear or Log Spacing?*

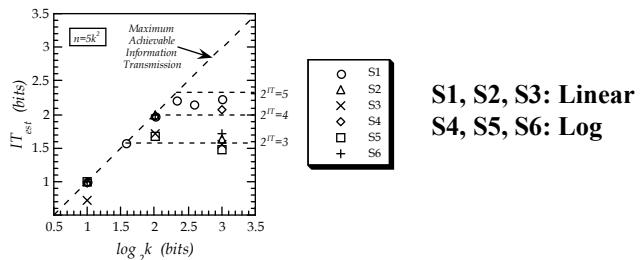
- **Objective**
  - ◆ Equal perceptual distance between adjacent stimuli
  - ◆ If Weber's law applies, logarithmic spacing is preferred
- **Problem**
  - ◆ Many discrimination experiments are required before an absolute identification exp can be designed and conducted
- **Lucky Solution**
  - ◆ In most cases, *information transfer* is not sensitive to stimulus spacing

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## An Example (Tan, 1997)

- Identification of sphere size:
    - ◆ Range of radius (fixed): 10.0 to 80.0 mm
    - ◆ Linear (e.g.,  $k=3$ ): 10.0, 45.0, 80.0 mm
    - ◆ Logarithmic (e.g.,  $k=3$ ): 10.0, 28.28, 80.0 mm



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## Issue #4: How Many Trials?

- The issue:
    - ◆  $IT_{est}$  is subject to statistical fluctuations
    - ◆  $IT_{est}$  is biased ( $E[IT_{est}] > IT$ )
    - ◆ bias > sampling errors
  - Need sufficient number of trials to overcome bias and sampling errors

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## Miller's (1954) Formula

- $IT_{est}$  is an over-estimate of  $IT$

$$E[IT_{est}] - IT = \frac{\log_2 e}{2n} (k-1)^2 + O\left(\frac{1}{n^2}\right) > 0$$

- With large  $n (> 5k^2)$ ,  $\Delta$  is small ( $0.14 \text{ bit}$ )
- With small  $n$ ,  $\Delta$  can over-correct  
i.e.,  $IT_{est} - \Delta < IT$

## Miller's (1954) Formula (cont.)

- When performance level is high,  $\Delta$  over-corrects

25	0	0	0
0	25	0	0
0	0	25	0
0	0	0	25

$P(C) = 100\%$   
 $IS = IR = IT_{est} = IT = 2 \text{ bits}$   
yet  $\Delta \neq 0$

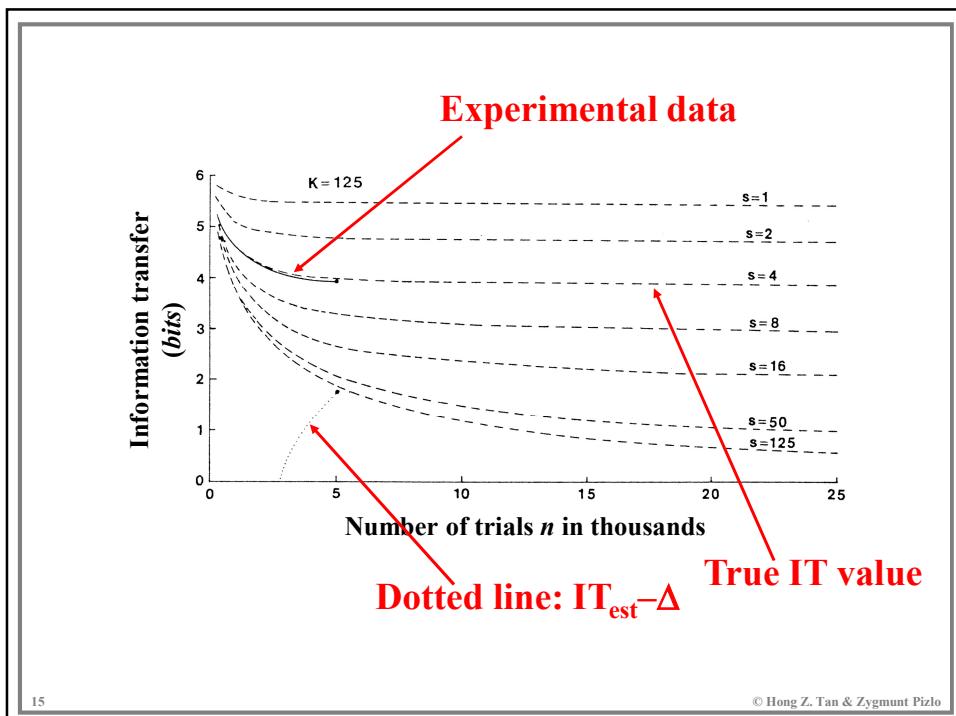
- Bottom line:  $n \geq 5k^2$  is needed.

## An Experiment where $k=125$ (Rabinowitz et al., JASA, 1987)

- For  $k = 125$ ,  $5k^2 = 78,125$  total trials!!
- 3-D stimulus set — pulsed sinusoidal vibration
  - ◆ Five values of intensity
  - ◆ Five values of contact area
  - ◆ Five values of frequency
- One-interval AI paradigm with feedback
- 3-tuples as responses (e.g., 111, 254, etc.)
- Data: 125-by-125 confusion matrix!!

## Houtsma's Computer Simulation (JASA, 1983)

- Assumption
  - ◆ 1-D experiment with  $k=125$
- Procedure
  - ◆ Randomly pick an  $S$  from 1-125;  $S \in [1, 125]$
  - ◆  $R_{raw} = S + noise (\pm s)$
  - ◆  $R$  is reset to 1 or 125 if  $R_{raw}$  is too small or too large;  
 $R \in [1, 125]$
  - ◆ Collect enough number of “trials”,  $n$
  - ◆ Estimate  $IT_{est}$  as a function of  $n$
- The value of  $s$  is used to control the asymptotic value of  $IT_{est}$



## So How Many Trials are Enough?

- Collect  $n \geq 5k^2$  trials if possible
- For one-dimensional stimuli,  $k$  is usually reasonable ( $7 \pm 2$ ).
- For multi-dimensional stimuli,
  - ◆ Additivity:  $IT(\text{multi-}D) = \sum IT(ID)$  ?
  - Usually,  $IT(A,F) < IT(A) + IT(F)$
  - ◆ A general additivity law (Durlach *et al.*, 1989)

## Issue #5: Training

- Training is usually needed for AI paradigms
- Criterion for termination of training

## Further Readings

- H. Z. Tan, “Identification of sphere size using the PHANToM™: Towards a set of building blocks for rendering haptic environment,” in *Proceedings of the ASME Dynamic Systems and Control Division*, vol. 61. Dallas, TX: American Society of Mechanical Engineers, 1997, pp. 197–203.
- G. A. Miller, “Note on the bias of information estimates,” in *Information Theory in Psychology*, H. Quastler (Ed.), 1954, pp. 95-100.

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- A. J. M. Houtsma, “Estimation of mutual information from limited experimental data,” *Journal of the Acoustical Society of America*, vol. 74, pp. 1626–1629, 1983.

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