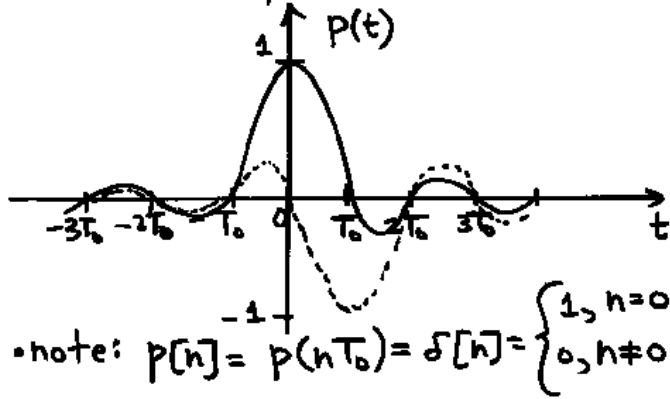


- for current US TDMA cellular standard, $\beta = 0.35$



- thus:

$$\begin{aligned}
 s[n] &= s(nT_0) \\
 &= \sum_{k=0}^{N-1} a[k] p(nT_0 - kT_0) \\
 &= \sum_{k=0}^{N-1} a[k] p[n-k] \\
 &= \sum_{k=0}^{N-1} a[k] \delta[n-k] \\
 &= a[n]
 \end{aligned}$$

- Note: bandwidth of $s(t)$ is $\frac{1+\beta}{2T_0}$

• where: $\frac{1}{T_0}$ is the bit rate

- Ideally, the Nyquist rate is

$$2 \left\{ \frac{1+\beta}{2T_0} \right\} = \frac{1+\beta}{T_0} \quad \text{where: } 0 < \beta < 1$$

- Consider sampling at bit rate nonetheless — sub-Nyquist sampling — assume synchronization

- despite:

- pulses overlapping in time (to have as high data rate in a given bandwidth)

- sub-Nyquist sampling

- can nonetheless recover the transmitted info. bits

- However, when multipath exists (reflections off buildings, etc.), the received signal is

$$x(t) = \sum_{l=1}^P g_l s(t - \tau_l)$$

• where: g_l : gain of l -th multipath

• τ_l : delay of " "

- $x(t)$ may be alternatively expressed as

$$x(t) = s(t) * \left\{ \sum_{l=1}^P g_l \delta(t - \tau_l) \right\}$$

$$x(t) = \sum_{k=0}^{N-1} a[k] p(t - kT_0) * \left\{ \sum_{l=1}^P g_l \delta(t - \tau_l) \right\}$$

$$= \sum_{k=0}^{N-1} a[k] q(t - kT_0)$$

$$q(t) = \sum_{l=1}^P g_l p(t - \tau_l)$$

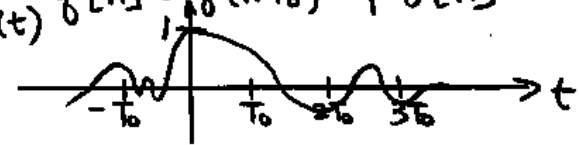
$$\begin{aligned} & \sum_l p(t - kT_0) * \delta(t - \tau_l) g_l \\ &= \sum_l p(t) * \delta(t - kT_0) * \delta(t - \tau_l) g_l \\ &= \sum_l p(t - \tau_l) * \delta(t - kT_0) g_l \\ &= \left\{ \sum_l g_l p(t - \tau_l) \right\} * \delta(t - kT_0) \\ &= q(t) * \delta(t - kT_0) \\ &= q(t - kT_0) \end{aligned}$$

- received signal:

$$x(t) = \sum_{k=0}^{N-1} a[k] q(t - kT_0)$$

- where: $q(t)$ is distorted pulse waveform due to multipath
 \Rightarrow Nyquist property is lost

$$q(t) \quad q[n] = q(nT_0) \neq \delta[n]$$



• sampling at bit rate:

$$\begin{aligned}
 x[n] &= x(nT_0) \\
 &= \sum_{k=0}^{N-1} a[k] g(nT_0 - kT_0) \\
 &= \sum_{k=0}^{N-1} a[k] g[n-k] \\
 &= a[n] * g[n] \quad \text{where: } g[n] \\
 &= \sum_{k=-M_1}^{M_2} g[k] a[n-k] = g(nT_0)
 \end{aligned}$$

• where ideally:

$$h[n] \neq 0 \text{ for } -M_1 < n < \infty$$

• Sidenote example:

$$g[n] = \delta[n] - a\delta[n-1]$$

$$Q(z) = 1 - az^{-1} = \frac{z-a}{z}$$

• Inverse System:

$$H(z) = \frac{1}{Q(z)} = \frac{z}{z-a} \Rightarrow h[n] = a^n u[n]$$

$$g[n] * h[n] = \delta[n]$$

$$a[n] \rightarrow \boxed{g[n]} \rightarrow x[n]$$

• Equalization is about how to determine $a[n]$ given $x[n]$

• a Zero-Forcing (ZF) Equalizer does this by means of inverse filtering:

$$x[n] \rightarrow \boxed{h[n]} \rightarrow y[n] = \hat{a}[n]$$

• where: $g[n] * h[n] = \delta[n]$

• adaptive filtering MMSE criterion

$$\text{Min}_{h[n]} E \left\{ \left[a[n] - \sum_{k=-M_1}^{N_2} h[k] x[n-k] \right]^2 \right\}$$

• where: $M_2 < N_2 < \infty$

• where: $g[n] \neq 0$ for $-M_1 < n < M_2$

• initially assume training sequence

• practically implement via LMS or RLS - see F1 Equalizer.m at course web site