

Session 21

## Recall...

21.1

Theorem: Let  $X$  and  $Y$  be two  
j-dist, independent RVs with  
marginal pdfs  $f_X(x)$  and  $f_Y(y)$ ,  
respectively. Then the pdf of  
their sum  $Z = X + Y$  is  
given by the convolution

$$\begin{aligned} f_Z(z) &= (f_X * f_Y)(z) \\ &= \int_{-\infty}^{\infty} f_X(x) f_Y(z-x) dx \\ &= \int_{-\infty}^{\infty} f_Y(y) f_X(z-y) dy. \end{aligned}$$

Example: Let  $X$  and  $Y$  be two i.i.d.

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independent exponential RVs, both with mean  $\mu$ . Let

$$Z = X + Y.$$

Find  $f_Z(z)$ .

$$f_Z(z) = \int_{-\infty}^{\infty} f_Y(y) f_X(z-y) dy$$

$$= \int_{-\infty}^{\infty} \frac{1}{\mu} \exp\left(-\frac{y}{\mu}\right) \cdot \frac{1}{\mu} \exp\left(-\frac{(z-y)}{\mu}\right) \cdot \mathbb{1}_{[0, \infty)}(y) \cdot \mathbb{1}_{[0, \infty)}(z-y) dy$$

$$= \int_0^z \frac{1}{\mu^2} \exp\left(-\frac{z}{\mu}\right) dy = \frac{z}{\mu^2} \exp\left(-\frac{z}{\mu}\right) \cdot \mathbb{1}_{[0, \infty)}(z).$$

## Two Functions of Two RVs

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Given two RVs  $X$  and  $Y$  with j-pdf  $f_{XY}(x,y)$ , and given two new RVs

$$Z = g(X, Y),$$

$$W = h(X, Y),$$

we want to find  $f_{ZW}(z,w)$ .

We will start by finding  $F_{ZW}(z,w)$ ,  
the joint cdf.

$$F_{Z,W}(z,w) = P(\{Z \leq z\} \cap \{W \leq w\})$$
$$= P(\{(X,Y) \in D_{z,w}\})$$

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where  $D_{z,w} \triangleq \{(x,y) \in \mathbb{R}^2 : g(x,y) \leq z \text{ and } h(x,y) \leq w\}$

$$\therefore F_{Z,W}(z,w) = \iint_{D_{z,w}} f_{X,Y}(x,y) dx dy, \quad \forall z,w \in \mathbb{R}$$

and then

$$f_{Z,W}(z,w) = \frac{\partial^2 F_{Z,W}(z,w)}{\partial z \partial w}$$

## Direct Joint Density Determination

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Theorem: Let  $X$  and  $Y$  be two  $j$ -dist RVs with  $j$ -pdf  $f_{X,Y}(x,y)$ . Let  $Z = g(X,Y)$  and  $W = h(X,Y)$ , and assume the functions  $g(x,y)$  and  $h(x,y)$  satisfy the following conditions:

(1) The equations  $z = g(x,y)$  and  $w = h(x,y)$  can be uniquely (simultaneously) solved for  $x$  and  $y$  in terms of  $z$  and  $w$ .

(2) The partial derivatives  $\frac{\partial x}{\partial z}$ ,  $\frac{\partial x}{\partial w}$ ,  $\frac{\partial y}{\partial z}$ ,  $\frac{\partial y}{\partial w}$  exist and are continuous.

...

(Theorem continued)

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Then the j-pdf of  $Z$  and  $W$  is

$$f_{ZW}(z,w) = f_{XY}(x(z,w), y(z,w)) \left| \frac{\partial(x,y)}{\partial(z,w)} \right|,$$

where the Jacobian is the determinant

$$\frac{\partial(x,y)}{\partial(z,w)} = \begin{vmatrix} \frac{\partial x}{\partial z} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial z} & \frac{\partial y}{\partial w} \end{vmatrix} = \frac{\partial x}{\partial z} \cdot \frac{\partial y}{\partial w} - \frac{\partial y}{\partial z} \cdot \frac{\partial x}{\partial w}.$$

Proof: See Papoulis

Example: Let  $X$  and  $Y$  be two zero-mean i.i.d. (independent, identically distributed) Gaussian RVs, both with variance  $\sigma^2$ .

$$f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y) = \frac{1}{2\pi\sigma^2} \exp\left\{-\frac{(x^2+y^2)}{2\sigma^2}\right\}.$$

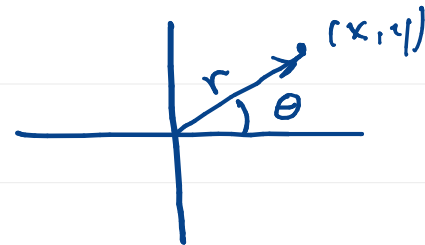
$$\text{Let } R \triangleq \sqrt{X^2 + Y^2} \text{ and } \Theta \triangleq \tan^{-1}(Y, X)$$

Find  $f_{R,\Theta}(r,\theta)$ .

$$r = \sqrt{x^2 + y^2}, \quad \theta = \tan^{-1}(y, x)$$

$$x(r, \theta) = r \cos \theta$$

$$y(r, \theta) = r \sin \theta$$





$$\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} \quad 21.8$$

$$= r \cos^2 \theta + r \sin^2 \theta = r (\underbrace{\cos^2 \theta + \sin^2 \theta}_1)$$

$$= r$$

$$\begin{aligned} \therefore f_{\mathbb{R}^2}(r,\theta) &= \int_{\mathbb{R}^2} f(x(r,\theta), y(r,\theta)) \left| \frac{\partial(x,y)}{\partial(r,\theta)} \right| \\ &= \frac{1}{2\pi\sigma^2} \exp \left\{ -\frac{(r^2 \cos^2 \theta + r^2 \sin^2 \theta)}{2\sigma^2} \right\} \cdot |r| \\ &= \frac{r}{2\pi\sigma^2} \exp \left\{ -\frac{r^2}{2\sigma^2} \right\} \cdot \mathbb{1}_{[0,\infty)}(r) \cdot \mathbb{1}_{(-\pi,\pi]}(\theta) \end{aligned}$$

n.b.

$$f_{\mathbb{R}^2}(r) = \int_{-\infty}^{\infty} f_{\mathbb{R}^2}(r, \theta) d\theta$$

$$= \int_{-\pi}^{\pi} \frac{r}{2\pi\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) \cdot \frac{1}{[0, \infty)} d\theta$$

$$= \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) \cdot \frac{1}{[0, \infty)}$$

$$f_{\mathbb{R}^2}(\theta) = ?$$

(exercise)

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We can loosen the constraints (1)  
and (2) of the last theorem...

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Theorem: Let  $X$  and  $Y$  be two  $j$ -dist RVs  
with  $j$ -pdf  $f_{XY}(x,y)$ , and let

$$Z = g(X, Y) \text{ and } W = h(X, Y).$$

To find  $f_{ZW}(z,w)$ , we must find  
all real solutions  $(x_n, y_n)$  such that

$$g(x_n, y_n) = z \text{ and } h(x_n, y_n) = w,$$

$$\text{for } n = 1, 2, \dots, N.$$

then

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$$\begin{aligned} f_{z,w}(z,w) &= f_{x,y}(x_1(z,w), y_1(z,w)) \left| \frac{\partial(x_1, y_1)}{\partial(z,w)} \right| \\ &+ \dots + f_{x,y}(x_N(z,w), y_N(z,w)) \left| \frac{\partial(x_N, y_N)}{\partial(z,w)} \right| \\ &= \sum_{n=1}^N f_{x,y}(x_n(z,w), y_n(z,w)) \cdot \left| \frac{\partial(x_n, y_n)}{\partial(z,w)} \right|. \end{aligned}$$

## Auxiliary Variables

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- Sometimes, we want to find the pdf of

$$Z = g(X, Y)$$

when  $f_{X,Y}(x,y)$  is given.

- It's often easier to use the direct technique  $(X, Y) \mapsto (Z, W)$  to find  $f_Z(z)$ .

- But we only have one RV  $Z$ .  
What do we do?

- You introduce an (arbitrary)  
auxiliary RV:

$$W = h(X, Y).$$

- Then you find  $f_{ZW}(z, w)$  using the direct pdf method.

- Then you integrate over  $w$  to get  $f_Z(z)$ :

$$f_Z(z) = \int_{-\infty}^{\infty} f_{ZW}(z, w) dw.$$

How do you pick the aux. RV  $W = h(X, Y)$ ?

Popular choices include

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$$W = X \quad \text{or} \quad |W| = \sqrt{X^2 + Y^2}$$

or

$$Z = \sqrt{X^2 + Y^2}$$

or

$$Z = \int (X^2 + Y^2)$$

You can pick

$$|W| = \tan^{-1}(Y, X)$$

In general, it can be trial-on-error guessing.

## Joint Moments

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Given two RVs  $X$  and  $Y$  and a RV

$$Z = g(X, Y),$$

we know that

$$E[Z] = \int_{-\infty}^{\infty} z f_Z(z) dz.$$

It is often easier to express  $E[Z]$  in terms of  $f_{X,Y}(x,y)$  and  $g(x,y)$ .



Theorem: Given two  $j$ -dist RVs  $X$  and  $Y$  with  $j$ -pdf  $f_{X,Y}(x,y)$ , and a new RV  $Z = g(X,Y)$ , we can compute

$$E[Z] = E[g(X,Y)]$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) dx dy$$

Proof: (Outline)

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Let  $\Delta D_z \triangleq \{ (x, y) \in \mathbb{R}^2 : z < g(x, y) \leq z + \Delta z \}$



Then for each differential element in the Riemann integral

$$E[z] = \int_{-\infty}^{\infty} z f_z(z) dz$$

there is a corresponding  $\Delta D_z$  in the  $xy$ -plane

As  $dz$  covers the whole real line,  
the corresponding  $\Delta D_z$  covers  
the whole  $x$ - $y$  plane in  $\mathbb{R}^2$ .

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These  $\Delta D_z$  do not overlap.

$$\int_{-\infty}^{\infty} z f_z(z) dz = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{x,y}(x,y) dx dy$$

$\therefore$  We can compute  $E[g(x,y)]$   
as

$$E[g(x,y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) \cdot f_{x,y}(x,y) dx dy$$

■

## Linearity of Expectation

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Let  $X$  and  $Y$  be two  $j$ -dist RVs with  $j$ -pdf  $f_{X,Y}(x,y)$ , and let

$$g_1(X,Y), g_2(X,Y), \dots, g_N(X,Y)$$

be functions of  $X$  and  $Y$ .

Then for constants  $\alpha_1, \alpha_2, \dots, \alpha_N$ ,

$$E\left[\sum_{n=1}^N \alpha_n g_n(X,Y)\right] = \sum_{n=1}^N \alpha_n E[g_n(X,Y)].$$

Proof: Exercise

Defn: Given two j-dist RVs  $X$  and  $Y$ ,

-the correlation between  $X$  and  $Y$  is defined as

$$\text{corr}(X, Y) \triangleq E[XY];$$

the covariance between  $X$  and  $Y$  is defined as

$$\text{cov}(X, Y) \triangleq E[(X - \bar{X})(Y - \bar{Y})];$$

-the correlation coefficient between  $X$  and  $Y$  is defined as

$$r_{XY} \triangleq \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y}$$

n.b.  $-1 \leq r_{xy} \leq 1$

Fact: If  $X$  and  $Y$  are statistically independent, then  $r_{xy} = 0$ .

Proof: (Exercise).

But, the converse is not true!

There is a special case where

$$r_{xy} = 0 \Rightarrow X \perp\!\!\!\perp Y$$

When  $X$  and  $Y$  are jointly Gaussian,

In this case  $r_{X,Y} = r$  in the  $j$ -Gaussian pdf.

$$\begin{aligned}
f_{X,Y}(x,y) &= \frac{1}{2\pi\sigma_x\sigma_y\sqrt{1-r^2}} \exp \left\{ \frac{-1}{2(1-r^2)} \left[ \frac{(x-\mu_x)^2}{\sigma_x^2} - 2r \frac{(x-\mu_x)(y-\mu_y)}{\sigma_x\sigma_y} + \frac{(y-\mu_y)^2}{\sigma_y^2} \right] \right\} \Big|_{r=0} \\
&= \frac{1}{2\pi\sigma_x\sigma_y} \exp \left\{ -\frac{1}{2} \left[ \frac{(x-\mu_x)^2}{\sigma_x^2} + \frac{(y-\mu_y)^2}{\sigma_y^2} \right] \right\} \\
&= \frac{1}{\sqrt{2\pi}\sigma_x} \exp \left\{ -\frac{(x-\mu_x)^2}{2\sigma_x^2} \right\} \cdot \frac{1}{\sqrt{2\pi}\sigma_y} \exp \left\{ -\frac{(y-\mu_y)^2}{2\sigma_y^2} \right\} \\
&= f_{X_1}(x) \cdot f_{Y_1}(y)
\end{aligned}$$

$\Rightarrow$  ~~X~~ || ~~Y~~

Defn: Two RVs  $X$  and  $Y$  are

uncorrelated if their covariance is equal to zero.

This is true if any one of the following equivalent conditions is true:

1.  $\text{Cov}(X, Y) = 0$

2.  $r_{XY} = 0$

3.  $E[XY] = E[X] \cdot E[Y]$ .

Defn: Two RVs  $X$  and  $Y$  are orthogonal if  $E[XY] = 0$ .



An example of a situation where  $X$  and  $Y$  are uncorrelated but not independent:

Suppose  $X \sim N[0, \sigma_x^2]$

Define  $Y = |X|$  ( $Y$  is not normal.)  
(exercise)

$$E[XY] = E[X \cdot |X|] = 0 \Rightarrow r_{XY} = 0$$

$$\text{cov}(X, Y) = E[X \cdot Y] - E[X] \cdot E[Y] = 0$$

$\therefore X$  and  $Y$  are uncorrelated

But clearly  $Y$  and  $X$  are not independent.  
( $Y = |X|$ )

Fact: If  $E[X^2] < \infty$  and  $E[Y^2] < \infty$ ,

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then

$$|E[XY]| \leq \sqrt{E[X^2] \cdot E[Y^2]},$$

with equality iff

$$Y = a_0 X,$$

(a.e.) almost everywhere.

for some constant  $a_0$ .

Proof:  $E[(aX - Y)^2] \geq 0$