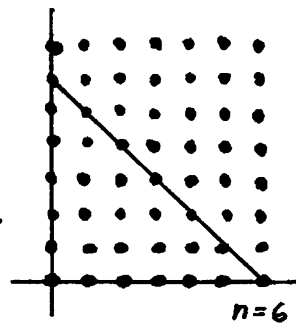


1. Papoulis 6-14: A plot of the point masses of the joint pmf appears as follows:

We wish to find the probability that  $Z = X + Y = n$ . This implies that  $X = k$  any  $Y = n - k$ , where  $k$  can take on values  $0, 1, 2, \dots, n$ . The possible  $(k, n - k)$ -pairs are  $(0, n), (1, n - 1), \dots, (n, 0)$ .

The probability of a particular  $(k, n - k)$  pair is



$$P(\{X=k\} \cap \{Y=n-k\}) = P(\{X=k\})P(\{Y=n-k\}) = a_k b_{n-k}.$$

Thus upon summing over all valid pairs for a given  $Z = X + Y = n$ , we get

$$P(\{Z=n\}) = \sum_{k=0}^n P(\{X=k\} \cap \{Y=n-k\}) = \sum_{k=0}^n a_k b_{n-k}.$$

2. Let us first look at the special case of  $\mu_x = \mu$  and  $\mu_y = 0$ . Thus we have  $X$  and  $Y$  are independent RVs having pdfs

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{(x-\mu)^2}{2\sigma^2}\right\}.$$

and

$$f_Y(y) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{y^2}{2\sigma^2}\right\}.$$

If we now define  $R = \sqrt{X^2 + Y^2}$  and  $\Theta = \tan^{-1}(Y, X)$  we can write

$$f_{R\Theta}(r, \theta) = f_{X,Y}(x(r, \theta), y(r, \theta)) \left| \frac{\partial(x, y)}{\partial(r, \theta)} \right|$$

$$\text{Now } x(r, \theta) = r \cos \theta,$$

$$y(r, \theta) = r \sin \theta,$$

and

$$\frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial y}{\partial r} \\ \frac{\partial x}{\partial \theta} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{vmatrix} = r(\cos^2 \theta + \sin^2 \theta) = r.$$

Thus we have

$$f_{R\Theta}(r, \theta) = f_X(r \cos \theta) \cdot f_Y(r \sin \theta) \cdot |r|$$

$$= \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{(r \cos \theta - \mu)^2}{2\sigma^2}\right\} \cdot \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{(r \sin \theta)^2}{2\sigma^2}\right\}$$

$$= \frac{r}{2\pi\sigma^2} \exp\left\{-\frac{(r^2 \cos^2 \theta + r^2 \sin^2 \theta - 2\mu r \cos \theta + \mu^2)}{2\sigma^2}\right\} \cdot \frac{1}{(0, \infty)}(r) \cdot \frac{1}{[0, 2\pi]}(\theta)$$

$$= \frac{r}{2\pi\sigma^2} \exp\left\{-\frac{(r^2 - 2r\mu \cos \theta + \mu^2)}{2\sigma^2}\right\} \cdot \frac{1}{(0, \infty)}(r) \cdot \frac{1}{[0, 2\pi]}(\theta)$$

$$\text{Thus } f_{IR}(r) = \int_{-\infty}^{\infty} f_{R\Theta}(r, \theta) d\theta = \frac{r}{2\pi\sigma^2} \exp\left\{-\frac{(r^2 + \mu^2)}{2\sigma^2}\right\} \int_0^{2\pi} e^{\frac{r\mu \cos \theta}{\sigma^2}} d\theta \cdot \frac{1}{(0, \infty)}(r)$$

$$\text{Now } I_0(x) = \frac{1}{2\pi} \int_0^{2\pi} e^{x \cos \theta} d\theta, \text{ as given in the problem.}$$

Thus we have

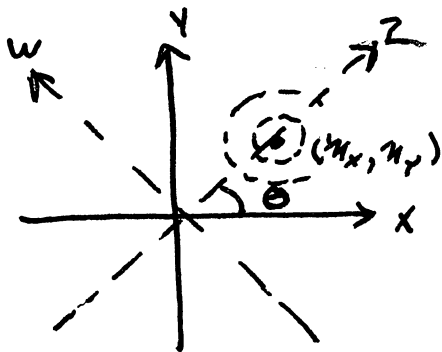
$$f_{IR}(r) = \frac{r}{\sigma^2} \exp\left\{-\frac{(r^2 + \eta^2)}{2\sigma^2}\right\} \cdot \underbrace{1_{(0,\infty)}(r)}_{\substack{1(r) \\ [9, \omega]}} \cdot \underbrace{\frac{1}{2\pi} \int_0^{2\pi} e^{\frac{r\eta}{\sigma^2} \cos \theta} d\theta}_{I_0\left(\frac{r\eta}{\sigma^2}\right)}$$

$$= \frac{r}{\sigma^2} \exp\left\{-\frac{(r^2 + \eta^2)}{2\sigma^2}\right\} I_0\left(\frac{r\eta}{\sigma^2}\right) \cdot 1_{(0,\infty)}(r)$$

Thus we have that the RV  $IR$  has a Rician p.d.f.:

$$f_{IR}(r) = \frac{r}{\sigma^2} \exp\left\{-\frac{(r^2 + \eta^2)}{2\sigma^2}\right\} I_0\left(\frac{r\eta}{\sigma^2}\right) \cdot 1_{(0,\infty)}(r)$$

Now let's look at the more general case where  $\eta_y \neq 0$ . Here we have a situation that appears as follows:



We have zero mean circular Gaussian noise added to  $(\eta_x, \eta_y)$

However if we rotate the axes clockwise by an angle  $\theta = \tan^{-1}(\eta_y, \eta_x)$ ,

we get two new random variables

$$Z = X \cos \theta + Y \sin \theta$$

$$W = -X \sin \theta + Y \cos \theta$$

We can write

$$f_{ZW}(z, w) = f_{XY}(x(z, w), y(z, w)) \left| \frac{\partial(x, y)}{\partial(z, w)} \right|$$

We note that

$$\begin{pmatrix} z \\ w \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ +\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} z \\ w \end{pmatrix}$$

$$\therefore \frac{\partial(x, y)}{\partial(z, w)} = \begin{vmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{vmatrix} = \cos^2 \theta + \sin^2 \theta = 1$$

P. 2C

Thus the circularly symmetric Gaussian noise with its means removed has the same pdf before and after rotating the axes. Thus we have if

$$W = \sqrt{Z^2 + Y^2}$$

We have the same problem we had before with  $R = \sqrt{X^2 + Y^2}$ , but now  $\mu_Z = \sqrt{\mu_X^2 + \mu_Y^2}$  and  $\mu_W = 0$ .

Thus we have

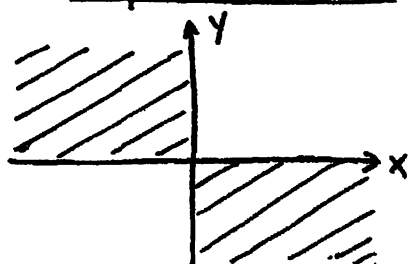
$$f_W(w) = \frac{w}{\sigma^2} \exp\left\{-\frac{w^2 + (\mu_X^2 + \mu_Y^2)}{2\sigma^2}\right\} I_0\left(\frac{w \sqrt{\mu_X^2 + \mu_Y^2}}{\sigma^2}\right) \cdot \frac{1}{(0, \infty)}$$

of course  $W = R$ , so we can rewrite this as

$$f_R(r) = \frac{r}{\sigma^2} \exp\left\{-\frac{r^2 + \mu_X^2 + \mu_Y^2}{2\sigma^2}\right\} I_0\left(\frac{r \sqrt{\mu_X^2 + \mu_Y^2}}{\sigma^2}\right) \cdot \frac{1}{(0, \infty)}$$

This approach of rotating circularly symmetric Gaussian noise is widely used in problems of detection, estimation, and communications theory.

3. Papoulis 6-18: If  $XY < 0$ , then  $(X, Y)$  must fall in one of the two shaded quadrants shown (excluding axes). Equivalently, we can write this as



$$\{XY < 0\} = \underbrace{(\{X < 0\} \cap \{Y > 0\}) \cup (\{X > 0\} \cap \{Y < 0\})}_{\text{disjoint events.}}$$

$$\begin{aligned} P(\{XY < 0\}) &= P((\{X < 0\} \cap \{Y > 0\}) \cup (\{X > 0\} \cap \{Y < 0\})) \\ &= P(\{X < 0\} \cap \{Y > 0\}) + P(\{X > 0\} \cap \{Y < 0\}) \\ &= P(\{X < 0\})P(\{Y > 0\}) + P(\{X > 0\})P(\{Y < 0\}), X \perp Y \end{aligned}$$


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(3 - continued)

P.3

$$\begin{aligned} &= F_X(0)[1 - F_Y(0)] + [1 - F_X(0)]F_Y(0) \\ &= \Phi\left(-\frac{\mu_X}{\sigma_X}\right)\left[1 - \Phi\left(-\frac{\mu_Y}{\sigma_Y}\right)\right] + \left[1 - \Phi\left(-\frac{\mu_X}{\sigma_X}\right)\right]\Phi\left(-\frac{\mu_Y}{\sigma_Y}\right) \\ &= \left[1 - \Phi\left(\frac{\mu_X}{\sigma_X}\right)\right]\Phi\left(\frac{\mu_Y}{\sigma_Y}\right) + \Phi\left(\frac{\mu_X}{\sigma_X}\right)\left[1 - \Phi\left(\frac{\mu_Y}{\sigma_Y}\right)\right] \\ &= \Phi\left(\frac{\mu_Y}{\sigma_Y}\right) - \Phi\left(\frac{\mu_X}{\sigma_X}\right)\Phi\left(\frac{\mu_Y}{\sigma_Y}\right) + \Phi\left(\frac{\mu_X}{\sigma_X}\right) - \Phi\left(\frac{\mu_X}{\sigma_X}\right)\Phi\left(\frac{\mu_Y}{\sigma_Y}\right) \\ &= \Phi\left(\frac{\mu_X}{\sigma_X}\right) + \Phi\left(\frac{\mu_Y}{\sigma_Y}\right) - 2\Phi\left(\frac{\mu_X}{\sigma_X}\right)\Phi\left(\frac{\mu_Y}{\sigma_Y}\right) \end{aligned}$$

n.b. In Papoulis's notation,  $G(\cdot) = \Phi(\cdot)$ , which is the cdf of a zero-mean, unit-variance Gaussian RV.

4. Papoulis 7-1: If  $W = X - Y$ , then  $E\{W\} = E\{X\} - E\{Y\} = 0$ .

$$\begin{aligned} \text{and } \sigma_W^2 &= E\{W^2\} = E\{X^2 - 2XY + Y^2\} \\ &= E\{X^2\} + 2E\{XY\} + E\{Y^2\} \\ &= \sigma_X^2 + \sigma_Y^2 = 2\sigma^2. \end{aligned}$$

Thus  $W \sim \mathcal{N}[0, \sigma\sqrt{2}]$ .  $Z \triangleq |X - Y| = |W|$

$$E\{Z\} = E\{|W|\} = \sigma\sqrt{2} \sqrt{\frac{2}{\pi}} = \frac{2\sigma}{\sqrt{\pi}} \quad (\text{see Eq. (5-45) of Papoulis}).$$

$$E\{Z^2\} = E\{|W|^2\} = E\{W^2\} = 2\sigma^2.$$

5. Papoulis 7-2:  $f_X(x) = e^{-x} \mathbf{1}_{[0, \infty)}(x)$ ,  $f_Y(y) = e^{-y} \mathbf{1}_{[0, \infty)}(y)$

Define  $Z \triangleq (X - Y)^+ = (X - Y) \mathbf{1}_{[0, \infty)}(X - Y) = g(X, Y)$

Show that  $E\{Z\} = \frac{1}{2}$ .

$$\begin{aligned} E\{Z\} &= E\{g(X, Y)\} = \iint_{\mathbb{R}^2} g(x, y) f_{X,Y}(x, y) dx dy \\ &= \int_0^\infty \int_0^\infty (x - y) e^{-x} e^{-y} \mathbf{1}_{[0, \infty)}(x - y) dx dy = \int_0^\infty \int_0^x (x - y) e^{-x} e^{-y} dy dx \\ &= \int_0^\infty [-x e^{-x} - e^{-x}]_y^x e^{-y} dy = \int_0^\infty e^{-2y} dy = \frac{e^{-2y}}{-2} \Big|_0^\infty = \frac{1}{2} \end{aligned}$$

6. Papoulis 7-3: For real or complex  $X$  and  $Y$ , show

P.4

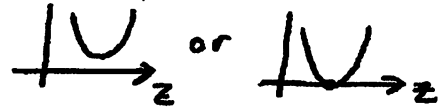
(a)  $|E\{XY\}|^2 \leq E\{|X|^2\} E\{|Y|^2\}$ :

Because  $|E\{XY\}| \leq E\{|X||Y|\}$ , we can assume  $X$  and  $Y$  are real. Then for any number  $z$ , we have that

$$E\{[zX - Y]^2\} = z^2 E\{X^2\} - 2z E\{XY\} + E\{Y^2\} \geq 0$$

This is a non-negative quadratic, having either no real roots, or one real root:

$\Rightarrow$  Its discriminant is non-positive.



$$\Rightarrow 4|E\{XY\}|^2 - 4E\{X^2\}E\{Y^2\} \leq 0$$

$$\Rightarrow |E\{XY\}|^2 \leq E\{X^2\}E\{Y^2\}$$

(b) Using the result of part (a), we have

$$E\{X^2\} + E\{Y^2\} + 2\sqrt{E\{X^2\}E\{Y^2\}} \geq E\{X^2\} + E\{Y^2\} + 2E\{XY\} = E\{(X+Y)^2\}$$

7. Papoulis 7-4: Show that if  $r_{XY} = 1$ , then  $Y = aX + b$

Recall that  $r_{XY} = \frac{E\{(X-\mu_X)(Y-\mu_Y)\}}{\sqrt{E\{(X-\mu_X)^2\} \cdot E\{(Y-\mu_Y)^2\}}} = \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y}$

If  $r_{XY} = 1$ , then this implies that

$$E^2\{(X-\mu_X)(Y-\mu_Y)\} = E\{(X-\mu_X)^2\} E\{(Y-\mu_Y)^2\},$$

that is, the Schwarz inequality is satisfied with equality for the RVs  $\tilde{X} = X - \mu_X$  and  $\tilde{Y} = Y - \mu_Y$ .

This implies that the discriminant of the quadratic...

(7 - continued)

P.5

$$\begin{aligned} E\{[z\tilde{X} - Y]^2\} &= E\{[z(X - \mu_X) - (Y - \mu_Y)]^2\} \\ &= z^2 E\{(X - \mu_X)^2\} - 2z E\{(X - \mu_X)(Y - \mu_Y)\} \\ &\quad + E\{(Y - \mu_Y)^2\} \quad (*) \end{aligned}$$

is equal to zero.

This is true because the discriminant is given by

$$4E^2\{(X - \mu_X)(Y - \mu_Y)\} - 4E\{(X - \mu_X)^2\}E\{(Y - \mu_Y)^2\}$$

If the discriminant is zero (as it is), the quadratic (\*) is zero for some real  $z = z_0$  (the unique real root).

$$\Rightarrow z_0(X - \mu_X) - (Y - \mu_Y) = 0$$

$$\Rightarrow Y - \mu_Y = z_0(X - \mu_X)$$

$$\Rightarrow Y = \underbrace{z_0}_{a} X + \underbrace{(\mu_Y - z_0 \mu_X)}_b = aX + b, \quad \begin{aligned} a &= z_0 \\ b &= \mu_Y - z_0 \mu_X \end{aligned}$$

8. Papoulis 7-7:  $X$  has Cauchy density  $f_X(x) = \frac{d}{\pi(d^2 + x^2)}$ ,

$$\Rightarrow \Phi_X(\omega) = E\{e^{i\omega X}\} = e^{-d|\omega|} \quad (\text{See problem 9 of Homework \#6}).$$

Now note that if  $W = kX$ ,  $k = 0, 1, 2, \dots$ , then

$$\Phi_W(\omega) = E\{e^{i\omega k X}\} = e^{-d|\omega|k}.$$

Now  $Z = NX$ , where  $N$  is an independent Poisson RV taking on non-negative integer values. So we have

$$\begin{aligned} \Phi_Z(\omega) &= E\{e^{i\omega Z}\} = E\{e^{i\omega NX}\} \\ &= E\{E\{e^{i\omega k X} \mid N=k\}\} = \sum_{k=0}^{\infty} E\{e^{i\omega k X}\} \cdot \frac{e^{-\lambda} \lambda^k}{k!} \\ &= e^{-\lambda} \sum_{k=0}^{\infty} \frac{[e^{-d|\omega|} \lambda]^k}{k!} = e^{-\lambda} e^{+\lambda e^{-d|\omega|}} \\ &= \exp\{\lambda e^{-d|\omega|} - \lambda\}. \end{aligned}$$



9. Papoulis 7-10:  $f_{XY}(x,y) = \frac{1}{4} \mathbb{1}_{[-1,1]}(x) \cdot \mathbb{1}_{[-1,1]}(y)$ .

Hence if  $R = \sqrt{X^2 + Y^2}$ ,  $P(\{R \leq 1\}) = \frac{\pi \cdot 1^2}{4} = \frac{\pi}{4}$

and

$$P(\{R \leq r\}) = \frac{\pi r^2}{4}, \text{ for } 0 \leq r \leq 1.$$

So  $P(\{R \leq r\} \cap \{R \leq 1\}) = \begin{cases} P(R \leq r), & r \leq 1 \\ P(R \leq 1), & r > 1 \end{cases}$

$$= \begin{cases} \pi r^2/4, & r \leq 1 \\ \pi/4, & r > 1 \end{cases}$$

Hence if  $M = \{R \leq 1\}$ ,

$$F_{IR}(r|M) = \frac{P(\{R \leq r\} \cap M)}{P(M)} = \begin{cases} r^2, & r \leq 1 \\ 1, & r > 1 \end{cases}$$

$$\Rightarrow f_{IR}(r|M) = \frac{dF_{IR}(r|M)}{dr} = 2r \cdot \mathbb{1}_{[0,1]}(r).$$

10. Papoulis 7-11: Let  $C_r = r$ -th coin selected

$A_k = k$  heads occur in  $n$  tossings.

From the random selection and independent tossings, it follows that  $P(C_r) = \frac{1}{m}$ ,  $r = 1, \dots, m$ .

$$P(A_k | C_r) = \binom{n}{k} p_r^k (1-p_r)^{n-k}$$

We wish to find  $P(C_r | A_k)$ . Since  $\{C_1, \dots, C_m\}$  form a partition of the sample space, Bayes' Theorem yields

$$P(C_r | A_k) = \frac{P(A_k | C_r) P(C_r)}{\sum_{i=1}^m P(C_i) P(A_k | C_i)} = \frac{\binom{n}{k} p_r^k (1-p_r)^{n-k} \cdot \frac{1}{m}}{\sum_{i=1}^m \frac{1}{m} \binom{n}{k} p_i^k (1-p_i)^{n-k}}$$

$$= (p_r^k (1-p_r)^{n-k}) / \left( \sum_{i=1}^m p_i^k (1-p_i)^{n-k} \right)$$

11. Papoulis 7-14: Recall that the Markov inequality states that for any nonnegative RV  $X$  and any  $\alpha > 0$

$$P(\{X > \alpha\}) \leq \frac{E\{X\}}{\alpha}$$

Now taking  $|Z|^2 = |X - Y|^2$  and  $\alpha = \varepsilon^2 > 0$ , we get

$$P(\{|Z|^2 > \varepsilon^2\}) \leq \frac{E\{|Z|^2\}}{\varepsilon^2} = \frac{E\{|X - Y|^2\}}{\varepsilon^2}$$

Thus

$$P(\{|X - Y| > \varepsilon\}) \leq \frac{E\{|X - Y|^2\}}{\varepsilon^2}$$